

CR Structures On Three Dimensional Contact Manifolds

Hatice Çoban

Middle East Technical University

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Presentation Outline

CR Structures
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Contact
Manifolds

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Motivation
For CR
Structures

What is a CR
manifold?

The Main
Theorem

Proof of the
theorem

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2 What is a CR manifold?

3 The Main Theorem

4 Proof of the theorem

The subject arose from a paper of Poincaré in which he considered whether the Riemann Mapping Theorem could be generalized from \mathbb{C}^1 to \mathbb{C}^2 . He showed that the analogous result does not hold in \mathbb{C}^2 by using two hypersurfaces of \mathbb{C}^2 are not equivalent.

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Different authors use different CR definitions. We use the following definition.

Definition

A CR structure on an odd dimensional manifold M^{2n+1} is a germ of a complex structure J on $\mathcal{O}(M \times \{0\}) \subset M \times \mathbb{R}$

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Embedded CR manifolds: Hypersurface type CR structures.
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Abstract CR manifolds:

- 1 (M, V) is a CR manifold if $\dim M = 2n + 1$, V is a subbundle of $\mathbb{C} \otimes TM$ with complex dimension $\dim V = n$, $V \cap \bar{V} = 0$ and $[V, V] \subset V$.

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- 2 (M, H, J) is a CR manifold if $\dim M = 2n + 1$, H is a real subbundle of TM with $\dim H = 2n$, $J : H \rightarrow H$ and $J^2 = -Id$.

If X and Y are in H , then so is $[JX, Y] + [X, JY]$ and

$$J\{[JX, Y] + [X, JY]\} = [JX, JY] - [X, Y]$$

If (M, ξ, J) are real analytic and satisfy the equation

$$X, Y \in \xi \Rightarrow [\tilde{J}X, \tilde{J}Y] - [X, Y] = \tilde{J}([\tilde{J}X, Y] + [X, \tilde{J}Y]) \in \xi$$

where $\tilde{J} = J|_{\xi}$ on ξ , then \tilde{J} extends to an integrable complex structure on $\mathcal{O}(M \times \{0\}) \subset M \times \mathbb{R}$.

Then the weaker definition of CR implies our definition.

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Theorem (Y. Ozan, H. Coban)

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Let M be a smooth orientable closed 3-manifold and ξ a contact structure on M . Then M admits a CR structure that induces a contact structure, which is isotopic to ξ .

- (M^{2n+1}, ξ) is a contact manifold if $\ker(\alpha) = \xi$ and $\alpha \wedge (d\alpha)^n \neq 0$.

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- (W^{2n}, ω) is a symplectic manifold if $d\omega = 0$ and $\omega^n \neq 0$.

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- (W^{2n}, ω) is a symplectic manifold if $d\omega = 0$ and $\omega^n \neq 0$.
- Let (N, ξ) , $\xi = \ker(\alpha)$ be a compact contact manifold then $(N \times \mathbb{R}, d(e^t\alpha))$ its symplectization.

In the proof, we use the fact that

- 1 Any closed smooth manifold is diffeomorphic to a nonsingular real algebraic set. Indeed more is true: If $M \subset \mathbb{R}^n$ is a closed smooth submanifold then it is isotopic to a nonsingular real algebraic set in \mathbb{R}^{n+1} . Then we may assume that any closed smooth manifold has a real analytic structure.

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- 1 Any closed smooth manifold is diffeomorphic to a nonsingular real algebraic set. Indeed more is true: If $M \subset \mathbb{R}^n$ is a closed smooth submanifold then it is isotopic to a nonsingular real algebraic set in \mathbb{R}^{n+1} . Then we may assume that any closed smooth manifold has a real analytic structure.
- 2 Tangent bundle of a nonsingular real algebraic variety is strongly algebraic. Differential forms on a real algebraic variety can be approximated by regular, in particular real analytic forms.

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From now on we identify M with X . Let $\alpha \in \Omega^1(X)$ be a smooth 1-form so that $\xi = \ker(\alpha)$. Using the coordinate chart

$$\phi : (-1/2, 1/2) \rightarrow U \subset S^1, \quad \phi(t) = e^{2\pi it}, \quad t \in (-1/2, 1/2),$$

define a smooth function $f : S^1 \rightarrow \mathbb{R}$ so that $f(t) = e^t$ if $|t| < 1/4$ and $f(t) = 0$ if $|t| \geq 1/3$. Then the 2-form $\omega = d(f(t)\alpha) \in \Omega^2(X \times S^1)$ is a symplectization of the contact structure in a neighborhood of X in $X \times S^1$.

The cotangent bundle of $X \times S^1$ is strongly algebraic and therefore the smooth 1-form $f(t)\alpha \in \Omega^1(X \times S^1)$ can be approximated in the C^∞ -topology by real algebraic (hence real analytic) 1-forms with arbitrary precision.

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Now, let $\beta \in \Omega^1(X \times S^1)$ be a real algebraic 1-form so close to $f(t)\alpha$ that its restriction to X is isotopic to α , as a contact form, and the 2-form $d\beta$ is still symplectic on an open neighborhood $U = X \times (-\epsilon, \epsilon)$ of X in $X \times S^1$. Moreover, the symplectic form on U is real algebraic and thus real analytic.

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Since ω and g are real analytic, there is a real analytic compatible J almost complex structure such that $\omega(u, v) = g(Ju, v)$.

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The almost complex structure on U gives a complex line distribution on T_*X , which is nothing but the contact structure given by the 1-form $\ker(\beta|_X)$. We know that this contact structure is isotopic to $\ker(\alpha) = \xi$. This complex line distribution on T_*X is integrable by dimension reasons.

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The complex structure J need not to be integrable on U . We can modify the almost complex structure on a neighborhood of X , without changing it on X , to an integrable complex structure on a possibly smaller open subset of U , but still containing X .

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The complex structure J need not to be integrable on U . We can modify the almost complex structure on a neighborhood of X , without changing it on X , to an integrable complex structure on a possibly smaller open subset of U , but still containing X .

This finishes the proof.

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THANK YOU!