Driving natural systems: Flux balance analysis of metabolism

Simplifying metabolic models

Solving FBA problems

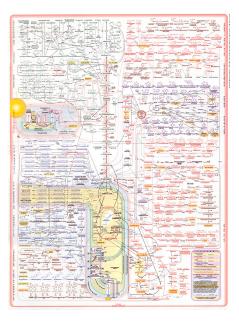
A working example of FBA

Uses of, and evolutionary insights from, FBA

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Driving natural systems: Flux balance analysis of metabolism

Complicated biochemical networks



- Biological metabolic and regulatory systems are incredibly complicated!
- Even if solvable, at what point does an ODE description of each term lose usefulness/interpretability? How robust is it to errors in parameters or missing data?

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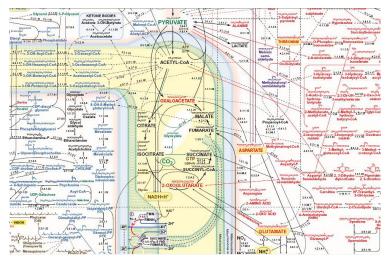
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Complicated biochemical networks

- We saw some of this subset yesterday...
- (Regarding these three lectures, knowledge of individual enzymes/reactants is explicitly non-examinable)



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Flux balance analysis

- Briefly, FBA is a simple way of simulating and optimising large metabolic systems, including the effects of perturbations, assuming a steady state
- Is a steady state assumption useful?
- Metabolite concentrations equilibrate fast (seconds) with respect to the timescale of genetic regulation (minutes) ... so a qualified yes
- Imagine we have a stochiometry matrix <u>S</u>

<i>s</i> ₁₁	<i>s</i> ₁₂	<i>s</i> ₁₃]
<i>s</i> ₂₁	s ₂₂	<i>s</i> ₂₃	
<i>s</i> ₃₁	s 32	s_{33}	
			···]

and a vector <u>v</u> describing the fluxes through each reaction

 $\left[\begin{array}{c} V_1\\ V_2\\ V_3\\ \dots \end{array}\right]$

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Flux balance analysis

- Stoichiometric matrix \underline{S} , vector of fluxes \underline{v} ; change in species with time $\frac{d\underline{X}}{dt} = \underline{Sv}$
- (the *i*th element of the vector <u>S</u>v gives the rate of accumulation or loss of species *i*)
- Balancing the fluxes means imposing $\underline{S} \underline{v} = \underline{0}$ (finding the steady state)
- We also probably want to bound \underline{v} (for example, $\underline{0} \leq \underline{v} \leq \underline{v}^{max}$)
- An important feature of <u>S</u> is that there are generally more reactions than chemical species, so the problem is underdetermined
- The solution space for any system of homogeneous equations and inequalities is a convex polytope

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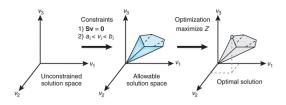
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Flux balance analysis

Stoichiometric matrix <u>S</u>, vector of fluxes <u>v</u>

- In general, many different ways exist to balance the fluxes in a system: set of possible <u>v</u> forms a convex polytope
- Each point in the polytope represents a set of fluxes at which the system can run at steady state
- We can find the solution that is optimal with respect to some feature that we are interested in
- Introduce a target function described by <u>c</u>; defined so that the quantity we want to maximise is <u>c</u> · <u>v</u>
- For example: if we're interested in producing chemical X, set c_i = 1 for i describing X → Ø, c_i = 0 otherwise



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- FBA is computationally cheap, needs only stoichiometric coefficients, no need for kinetic parameters
- FBA doesn't uniquely specify a solution, is difficult to use dynamically, isn't perfect (e.g. regulatory loops), and creating the stochiometric matrix is a non-trivial exercise in curation

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Input, output, accumulation and dummy reactions

- Assume zero accumulation, thus working in a steady-state picture
- Introduce input and output 'reactions': flux of reactants and products into and out of the system
- Maximise the dummy output flux of products of interest to maximise production of these products
- Problem is to maximise $\underline{c} \cdot \underline{v}$ subject to $\underline{S} \, \underline{v} = \underline{0}$ and $\underline{0} \leq \underline{v}$
- This problem falls into *linear programming* (maximise a function within a convex polytope)

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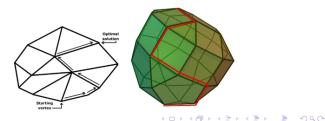
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Linear programming

- Dantzig's simplex algorithm: 'the algorithm that rules the world' according to New Scientist
- Locate extreme points (vertices) of the polytope
- For a standard linear program, if the objective function has an optimal value in the convex polytope, then it has this value on at least one extreme point of the polytope
- If an extreme point is not a minimum, there is an edge containing that point such that the objective function gets better along that edge away from the point
- If that edge is finite, we take it and find a better point; otherwise, the problem is unbounded and has no solution
- Some problems: potential cycling if points are degenerate; exponential worst-case. Many alternatives: refined pivoting; criss-cross; conic sampling; other algorithms for interior points in more complicated contexts



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- Step 1: write problem using 'slack variables' to set up equalities.
- Minimise r = -2x 3y 4z given

becomes

$$3x + 2y + z + s + 0t = 10$$

$$2x + 5y + 3z + 0s + t = 15$$

$$x, y, z, s, t > 0$$

Step 2: write the problem in tableau form

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A tableau gives a 'basic feasible solution': identify columns with one unit entry

$$\begin{bmatrix} 1 & 2 & 3 & 4 & 0 & 0 & 0 \\ 0 & 3 & 2 & 1 & 1 & 0 & 10 \\ 0 & 2 & 5 & 3 & 0 & 1 & 15 \end{bmatrix}$$
(2)

- The corresponding variables take values from the final column; other variables are zero (x = y = z = 0, s = 10, t = 15)
- Step 3: identify a 'pivot' column need a positive entry in the top row

$$\begin{bmatrix} 1 & 2 & 3 & 4 & 0 & 0 & 0 \\ 0 & 3 & 2 & 1 & 1 & 0 & 10 \\ 0 & 2 & 5 & 3 & 0 & 1 & 15 \end{bmatrix}$$
(3)

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- Step 4: identify the pivot row.
- Minimise (entry in final column) / (entry in pivot column) over all rows

Γ	1	2	3	4	0	0	0]	
	0	3	2	1	1	0	10	
L	0	2	5	3	0	1	0 10 15	

- 15/3 > 10/1: choose row 3.
- Step 5: multiply pivot row by the reciprocal of pivot entry (e.g. 3)

Step 6: add linear multiples of pivot row to tableau such that pivot column entry is zero (e.g. row 1 = row 1 - 4/3× row 3; row 2 = row 2 - row 3)

$$\begin{bmatrix} 1 & -2/3 & -11/3 & 0 & 0 & -4/3 & -20 \\ 0 & 7/3 & 1/3 & 0 & 1 & -1/3 & 5 \\ 0 & 2/3 & 5/3 & 1 & 0 & 1/3 & 5 \end{bmatrix}$$
(6)

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(4)

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 Repeat until we have no positive entries corresponding to variables in the top row.

$$\begin{bmatrix} 1 & -2/3 & -11/3 & 0 & 0 & -4/3 & -20 \\ 0 & 7/3 & 1/3 & 0 & 1 & -1/3 & 5 \\ 0 & 2/3 & 5/3 & 1 & 0 & 1/3 & 5 \end{bmatrix}$$
(7)

- We're done!
- Basic feasible solution:

$$\begin{bmatrix} 1 & -2/3 & -11/3 & 0 & 0 & -4/3 & -20 \\ 0 & 7/3 & 1/3 & 0 & 1 & -1/3 & 5 \\ 0 & 2/3 & 5/3 & 1 & 0 & 1/3 & 5 \end{bmatrix}$$
(8)

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 \rightarrow *z* = 5, *s* = 5, *x* = *y* = *t* = 0.

Solution r = -2x - 3y - 4z = -20.

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Evolution and biological optimisation

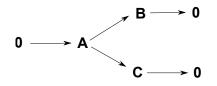
- Is it reasonable to expect natural systems to find optimal solutions?
- Evolution is a powerful optimiser, particularly in systems with large populations and small generation times (for example, bacteria)
- Growth rate is often explored with FBA: a reasonable proxy for 'fitness' in bacterial populations
- How is growth rate predicted? Often, biomass production; also arguments for ATP production.
- e.g. E. coli:
 0.33G6P + 0.07F6P + 0.96R5P + 0.36E4P + 0.36GA3P + 0.863PG + 0.77PEP +
 2.94PYR + 2.41ACCOA + 1.65OA + 1.28AKG + 15.7NADPH + 40.2ATP → BM + 3NADH (Schuetz et al. MSB 3 119 (2007))
- Can also consider nonlinear and/or nonconvex objectives: need more general solvers.
- As we will see, bacterial systems can evolve to find optimal solutions on reasonable human timescales
- Variants of flux balance analysis also allow us to explore transient phenomena

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- All reactions irreversible
- Sources and sinks allow balance

$$\underline{\underline{S}}^{T} = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ -1 & 0 & 1 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

Trivial example: maximise production of B

$$\underline{\mathbf{C}} = \begin{bmatrix} 0\\0\\0\\1\\0 \end{bmatrix}$$

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$$\underline{\underline{S}}^{T} = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ -1 & 0 & 1 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}; \ \underline{\underline{C}} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}$$

- Find the \underline{v} that maximises $\underline{c} \cdot \underline{v}$ such that $\underline{Sv} = \underline{0}$ and $\underline{0} \leq \underline{v} \leq \underline{1}$
- Worth knowing the appropriate MATLAB command: linprog
- v = linprog(-c, [], [], S, zeros(1,N), a, b)
- First argument -<u>c</u> because linprog is a minimisation tool
- Empty arguments 2 & 3 allow constraints of the form $Sv \leq w$
- Arguments 4 & 5 impose Sv = 0
- Arguments 6 & 7 bound \underline{v} with $\underline{a} \leq \underline{v} \leq \underline{b}$

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$$\underline{\underline{S}}^{T} = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ -1 & 0 & 1 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}; \ \underline{\underline{C}} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}$$

In this case v = linprog(-c, [], [], S, zeros(1,N), a, b) with <u>a</u> = <u>1</u>, <u>b</u> = <u>0</u> straightforwardly gives

$$\underline{v} = \begin{bmatrix} 1\\1\\0\\1\\0 \end{bmatrix}$$

$$\mathbf{B} \longrightarrow \mathbf{0}$$

$$\mathbf{A} \xrightarrow{\mathbf{C}} \mathbf{C} \xrightarrow{\mathbf{X}} \mathbf{0}$$

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$$\underline{\underline{S}}^{T} = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ -1 & 0 & 1 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}; \ \underline{\underline{c}} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}$$

• What if the reaction $A \rightarrow C$ keeps us alive?

- We can solve with a lower bound on flux through this reaction: $a_3 = 0.1$.
- In this case v = linprog(-c, [], [], S, zeros(1,N), a, b) unsurprisingly gives

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$$\underline{v} = \begin{bmatrix} 0.9\\ 0.1\\ 0.9\\ 0.1 \end{bmatrix}$$

$$B \longrightarrow 0$$

$$C \longrightarrow 0$$

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Deleting and restricting reactions

- ▶ v = linprog(-c, [], [], S, zeros(1, N), a, b) finds \underline{v} that maximises $\underline{c} \cdot \underline{v}$ such that $\underline{Sv} = \underline{0}$ and $\underline{a} \leq \underline{v} \leq \underline{b}$
- Removing single reactions in turn allows identification of the key reactions for production of a target (e.g. biomass)
- Many reactions are catalysed by specific enzymes: identification of critical reactions can thus be used to choose drug targets
- Extension to multiple reaction deletions (e.g. pairwise) for promiscuous enzymes
- Bounds in linear programming can be used to "knock down" rather than "knock out" reactions
- Set appropriate $b_i = 0$ or $b_i = b_i^{max}$

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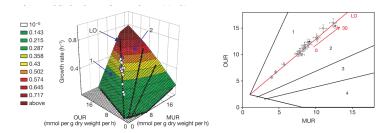
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Evolution and optimality

- E. coli wildtype evolved to use several different food sources
- When grown on malate,
 - Growth rates against oxygen and malate uptake closely match FBA predictions
 - Initial positions lie on optimal extreme path; evolution drives further increase along this path



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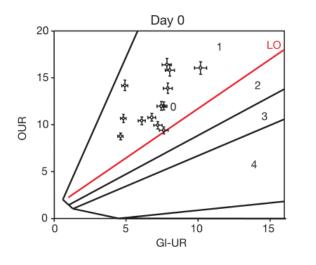
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Evolution and optimality

When grown on glycerol – an unnatural, but passable, sole foodstuff – metabolism is initially far from optimal...



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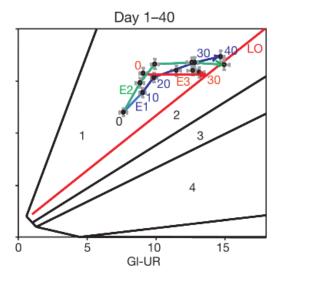
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Evolution and optimality

 ... but evolution locates the optimal (and accurately predicted) metabolic profile after 40 days (~700 generations)



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- Flux variability analysis: for degenerate optima, determines the range of parameters that gives rise to the optimal solution
- Minimisation of metabolic adjustment: attempts to predict transient behaviour in response to perturbation by minimising distance between standard and perturbed fluxes
- Quadratic programming: minimise $||\underline{v}_{WT} \underline{v}_{\mu}||^2$ such that $\underline{\underline{S}v}_{\mu} = \underline{0}$
- Other approaches to dynamics: regulatory on-off minimisation; iterated dynamic FBA

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