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Similarly, any $n \times n$ matrix has a minimal polynomial.

Prop 19.1 Let $T: V \rightarrow V$ linear map, V vector space over F .

1) T has a unique minimal poly $m_T(x) \in F[x]$.

2) For $p(x) \in F[x]$,

$$p(T) = 0 \iff m_T(x) \text{ divides } p(x)$$

Rg Sheet 8, Q1.

Prop 19.2 $T: V \rightarrow V$ linear map.

1) $m_T(x)$ divides ~~the~~ the characteristic poly of T .

2) If λ is an eigenvalue of T , then λ is a root of $m_T(x)$.

Rg 1) Cayley-Ham + 19.1(2).

2) let

$$T(v) = \lambda v, \quad (v \neq 0)$$

Then

$$0 = m_T(T)(v) = m_T(\lambda)v.$$

$$\text{Hence } m_T(\lambda) = 0.$$

Ex. 1) Min. poly of I is $x-1$.

2) Min poly of $J = J_n(\lambda)$:

Well, char. poly of J is $(x-\lambda)^n$.

We also know

$$(J-\lambda I)^{n-1} \neq 0.$$

Therefore min poly. is $(x-\lambda)^n$.

3) If $\rightarrow A$ $n \times n$ over \mathbb{C} ,

with distinct eigenvalues $\lambda_1, \dots, \lambda_k$

has min poly

$$m_A(x) = \prod_{i=1}^k (x-\lambda_i)^{r_i}$$

where r_i is the size of largest λ_i -block

is the JCF of A .

(Sheet 8, Q22).

20. Direct sums

Let V be a vector space,

with subspaces V_1, \dots, V_k .

We write

$$V = V_1 \oplus V_2 \oplus \dots \oplus V_k$$

if, for every $v \in V$, there are

unique vectors $v_i \in V_i$ s.t.

$$v = v_1 + v_2 + \dots + v_k.$$

If ~~it~~ holds, we say V is the direct sum of the subspaces V_1, \dots, V_k .

Ex. $\mathbb{R}^2 = \text{Sp}(1,0) \oplus \text{Sp}(0,1)$

Prop 20.1 The following are

equivalent:

1) $V = V_1 \oplus V_2$

2) $V_1 \cap V_2 = \{0\}$ and

$\dim V = \dim V_1 + \dim V_2$

Ex. sheet 8, Q6. ✓

Prop 20.2 The following are

equivalent:

1) $V = V_1 \oplus \dots \oplus V_k$

2) $\dim V = \sum_{i=1}^k \dim V_i$,

and if B_i is a basis of V_i then

$B = B_1 \cup \dots \cup B_k$

is a basis of V .

Pf (1) \Rightarrow (2) Assume

$$V = V_1 \oplus \dots \oplus V_k.$$

Let B_i be a basis of V_i

for each i , and

$$B = B_1 \cup \dots \cup B_k.$$

Claim B is a basis of V .

Pf a) B spans V : clear,

since $V = V_1 + \dots + V_k$.

b) B lin. indep

Suppose

$$\textcircled{B} \sum_{b \in B_1} \alpha_b b + \dots + \sum_{c \in B_k} \gamma_c c = 0$$

(where coeffs $\alpha_b, \dots, \gamma_c \in F$).

~~Since~~ Now

$$0 = 0 + \dots + 0$$

is the unique expression for 0 as a sum in $V_1 + \dots + V_k$.

Hence each term in LHS

of \textcircled{B} is 0 , and hence

all coeffs $\alpha_b, \dots, \gamma_c$ are 0 .

Hence B is a basis of V .

(2) \Rightarrow (1) Assume (2):

$B = B_1, v, \dots, v, B_k$ is a basis

of V . Clearly, then

$$V = V_1 + \dots + V_k.$$

Suppose $v \in V$ has expressions

$$v = v_1 + \dots + v_k = v'_1 + \dots + v'_k$$

$(v_i, v'_i \in V_i)$. Then

$$0 = (v_1 - v'_1) + \dots + (v_k - v'_k).$$

If any $v_i - v'_i$ is not 0, this will give a linear relation among the vectors in B ~~\times~~ .

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Hence $v_i = v'_i \forall i$, and so

$$V = V_1 \oplus \dots \oplus V_k. \quad \checkmark$$

Ex. $V = \mathbb{R}^4$. Let

$$V_1 = \text{Sp} \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \end{pmatrix} = \text{Sp}(v_1, v_2)$$

$$V_2 = \text{Sp} \begin{pmatrix} 2 & 1 & 2 & 1 \end{pmatrix} = \text{Sp}(v_3)$$

$$V_3 = \text{Sp} \begin{pmatrix} 0 & 0 & 1 & 1 \end{pmatrix} = \text{Sp}(v_4)$$

Qn Is $\mathbb{R}^4 = V_1 \oplus V_2 \oplus V_3$?

Ans ~~\times~~ By 20.2(2), need

to check whether

$$v_1, v_2, v_3, v_4$$

is a basis of \mathbb{R}^4 .

well,

$$\begin{pmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{pmatrix} \rightarrow \begin{pmatrix} * \\ * \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

So nd a basis.

Direct sums and linear maps

Prop 20.3 Let

$$V = V_1 \oplus \dots \oplus V_k$$

with basis $B = B_1 \cup \dots \cup B_k$

(B_i : basis of V_i). Let $T: V \rightarrow V$

be a linear map, and suppose

each V_i is T -invariant.

Let $T|_{V_i}$ be the restriction of T to V_i , and

$$A_i = [T|_{V_i}]_{B_i}$$

Then

$$[T]_B = A_1 \oplus \dots \oplus A_k$$

$$= \begin{pmatrix} A_1 & & 0 \\ & A_2 & \\ 0 & & \ddots \\ & & & A_k \end{pmatrix},$$

block-diagonal matrix.

\mathbb{R} . As V_1 is T invariant,

$T(V_1) \subseteq V_1$, and this implies

top left block of $[T]_{\mathcal{B}}$ is

$[T_{V_1}]_{\mathcal{B}_1}$, and so on. \checkmark

Prop 20.4 Let $T: V \rightarrow V$

with V over \mathbb{C} , with char poly

$$p(x) = \prod_{i=1}^k (x - \lambda_i)^{a_i}$$

where $\lambda_1, \dots, \lambda_k$ are the distinct eigenvalues of T . Define for $1 \leq i \leq k$

$$V_i = \ker (T - \lambda_i I)^{a_i}$$

Then

$$V = V_1 \oplus \dots \oplus V_k.$$

Define the subspaces ~~V_i~~ .

$$V_i = \ker (T - \lambda_i I)^{a_i}$$

are the generalized eigenspaces

of T .

Pf. Seelet 8, Q8.

Ex $V = \mathbb{C}^3$, $T: V \rightarrow V$ given by

$$T(v) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 1 & 1 & 0 \end{pmatrix} v$$

Char poly: $\chi^2(\chi-1)$.

Generalised eigenspaces

$$V_1 = \ker(T-I) = \text{Sp}(e_1, e_3)$$

$$V_2 = \ker T^2 = \text{Sp}(e_2, e_3).$$

Then $B = B_1 \cup B_2 = \{e_1, e_2, e_3\}$

is a basis of V , so $V = V_1 \oplus V_2$

and

$$[T]_B = \left(\begin{array}{c|cc} 1 & 0 & 0 \\ \hline 0 & 0 & 0 \\ 0 & 1 & 0 \end{array} \right) = \begin{pmatrix} A_1 & 0 \\ 0 & A_2 \end{pmatrix}.$$

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Let $T: V \rightarrow V$ have char. poly

$$p(x) = \prod_1^k (x - \lambda_i)^{a_i}$$

and

$$V_i = \ker (T - \lambda_i I)^{a_i}$$

so that

$$V = V_1 \oplus \dots \oplus V_k$$

as in Prop 20.4.

Let $B = B_1, \dots, B_k$

basis of V , where B_i basis

of V_i .

Prop 20.5

1) Each V_i is T -invariant.

2) If $A_i = [T|_{V_i}]_{B_i}$, then

$$[T]_B = A_1 \oplus \dots \oplus A_k$$

3) The only eigenvalue of A_i

is λ_i .

$$P.B. 1) v \in V_i \Rightarrow (T - \lambda_i I)^{a_i}(v) = 0$$

$$\Rightarrow T(T - \lambda_i I)^{a_i}(v) = 0$$

$$\Rightarrow (T - \lambda_i I)^{a_i} T(v) = 0$$

$$\Rightarrow T(v) \in V_i$$

(2) follows from 20.2

(3) As $V_i = \ker (T - \lambda_i I)^{a_i}$,

$$(T_{V_i} - \lambda_i I)^{a_i} = 0$$

(the zero linear map $V_i \rightarrow V_i$).

Hence the only eigenvalue of

T_{V_i} is λ_i . //

Final remark By 20.5, to

prove the JCF Thm. 18.3(1),

it's enough to prove it for

the matrices A_i , i.e. for matrices having a single eigenvalue.

21. The JCF theorem for matrices with a single eigenvalue.

Let $\dim V = n$, $T: V \rightarrow V$

and suppose T has only one eigenvalue λ . Then char.

poly. is $(x - \lambda)^n$, so by C-H

$$(T - \lambda I)^n = 0$$

Define $S = T - \lambda I$.

Then $S^n = 0$ and the only
eigenspace of S is 0 .

JCF from 18.3(1) for S :

Theorem 21.1 Let $\dim V = n$,

and $S: V \rightarrow V$ linear map

st. $S^n = 0$. Then \exists basis \mathcal{B}

such that

$$[S]_{\mathcal{B}} = J_{n_1}(0) \oplus \dots \oplus J_{n_k}(0).$$

Cor. 21.2 Then for

$$T = S + \lambda I$$

we have

$$[T]_{\mathcal{B}} = J_{n_1}(\lambda) \oplus \dots \oplus J_{n_k}(\lambda)$$

(which is the JCF from 18.3(1)

for T).

Rf of Thm 2.1.1

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Want to find basis B s.t.

$$[S]_B = \begin{pmatrix} 0 & 1 & & & \\ & 0 & 1 & & \\ & & \ddots & \ddots & \\ & & & 0 & 1 \\ & & & & 0 \end{pmatrix} \oplus \dots \oplus J_{n_1}(0)$$

So want basis ordered $v_1, \dots, v_{n_1}, \dots$

s.t.

$$S(v_1) = v_2, S(v_2) = v_3, \dots, S(v_{n_1}) = 0.$$

So basis B should start

$$v_1, S(v_1), S^2(v_1), \dots, S^{n_1-1}(v_1)$$

(actually the reverse of this)

$$\text{where } S^{n_1}(v_1) = 0.$$

So we are looking for a basis of V of the form

$$v_1, S(v_1), \dots, S^{n_1-1}(v_1), \\ \vdots \\ v_k, S(v_k), \dots, S^{n_k-1}(v_k)$$

where $S^{n_1}(v_1) = 0, \dots, S^{n_k}(v_k) = 0$
(Jordan basis).

We prove such a basis exists
by induction on $n = \dim V$.

Clear for $n = 1$.

Assume true for vector spaces
of dim $\leq n$.

Let

$$\dim(S) = S(V) \subseteq V.$$

As 0 is an evctue, $\ker(S) \neq 0$,

so $S(V) \neq V$, i.e.

$$\dim S(V) < n.$$

Let

$$W = S(V).$$

The W is S -invariant, so

$$S(W) = S(S(V)) \subseteq S(V) = W.$$

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Apply induction to the
restriction

$$S_W : W \rightarrow W.$$

So here is a Jordan basis

(as $W \cong S(V)$):

$$\underbrace{u_1, S(u_1), \dots, S^{m_1-1}(u_1), \dots}_{\vdots}$$

$$\underbrace{u_r, S(u_r), \dots, S^{m_r-1}(u_r)}$$

where $S^{m_i}(u_i) = 0$ $\forall i$ and

$$\sum_{i=1}^r m_i = \dim W.$$

Now we add vectors to this:

1) As each $u_i \in W = S(V)$,

$\exists v_i \in V$ s.t. $u_i = S(v_i)$.

Add v_i to the list V_i .

2) Note $\ker(S)$ contains the

lin. indep vectors

$$S^{m_1-1}(u_1), \dots, S^{m_r-1}(u_r)$$

Expand this to a basis of

$\ker(S)$ by adding further

vectors w_1, \dots, w_s .

Note

$$\dim(\ker(S)) = r+s.$$

Adding the v_i 's and w_i 's
to the list $\boxed{V_i}$, now have
a new list of s vectors

$$v_1, S(v_1), S^2(v_1), \dots, S^{m_1}(v_1),$$

\downarrow
 u_1

$$S(v_1)$$

\vdots



$$v_r, S(v_r), \dots, S^{m_r}(v_r),$$

$$w_1, \dots, w_s$$



Claim The list $\boxed{V_i}$ is

a Jordan basis of V

(of form $\textcircled{2}$).

Pf. Linearly independent Suppose \exists linear

relation

$$\alpha_1 v_1 + \dots + \alpha_{m+1} S^{m_1}(v_1)$$

$$+ \dots + \beta_1 v_r + \dots + \beta_{m_r+1} S^{m_r}(v_r) \quad (1)$$

$$+ \delta_1 w_1 + \dots + \delta_s w_s = 0$$

Apply S , noting $S^{m_i+1}(v_i) = 0 \forall i$

get

$$\alpha_1 S(v_1) + \dots + \alpha_{m_1} S^{m_1}(v_1)$$

$$+ \dots + \beta_1 S(v_r) + \dots + \beta_{m_r} S^{m_r}(v_r) = 0$$

$$(\text{under } S(w_i) = 0 \forall i).$$

This is a linear relation

on the basis $\{v_i\}$ of $S(V)$

Hence

$$\alpha_1 = \dots = \alpha_{m_1} = \dots = \beta_1 = \dots = \beta_{m_r} = 0$$

Now eqn (1) is

$$\alpha_{m_1+1} S^{m_1}(v_1) + \dots + \beta_{m_r+1} S^{m_r}(v_r) + \sum_{i=1}^s \delta_i w_i = 0.$$

This is a linear relation on a basis of $\text{ker}(S)$, so

all coeffs are 0:

$$\alpha_{m_1+1} = \dots = \beta_{m_r+1} = \delta_i = 0 \forall i.$$

This proves linear independence

\mathcal{B}_b is

Basis No. of vectors is hd

\mathcal{B}_b is

$$(m_1+1) + \dots + (m_r+1) + s$$

$$= \sum_1^r m_i + r + s$$

$$= \dim W + \dim(\text{Ker } S)$$

$$= \dim(\text{Im } S) + \dim(\text{Ker } S)$$

$$= \dim V = n.$$

Hence \mathcal{B}_b is a basis

Finally, if \mathcal{B} is the basis \mathcal{B}_b (with each

row sequence in the first r rows reversed), then

$$[S]_{\mathcal{B}} = J_{m_1+1}(0) \oplus \dots \oplus J_{m_r+1}(0) \oplus J_1(0) \oplus \dots \oplus J_1(0),$$

$\xleftarrow{s} \quad \xrightarrow{s}$

a JCF,

This completes the proof of JCF Th 18.3(1) by induction. //

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Defn Let $T: V \rightarrow V$ linear map.

A basis B of V such that

$[T]_B$ is a JCF, is called

a Jordan basis of V .

Ex. Find a Jordan basis for

$S: \mathbb{C}^4 \rightarrow \mathbb{C}^4$ defined by

$$S(v) = \begin{pmatrix} 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix} v$$

Ans Note only eigenvalue

of S is 0 , char. poly x^4 .

Strategy from the idempotent pt

¶ 2.1.1:

Step 1 Let

$$W = S(V) = \text{Sp}(e_1, e_2, e_3).$$

Step 2 Compute Jordan basis

~~of~~ $S_W: W \rightarrow W$:

$$u_1, S(u_1)$$

where $u_1 = e_2 + e_3$.

Step 3 Add further vectors

1) Add v_1 s.t. $u_1 = S(v_1)$;

take $v_1 = e_4$.

2) Extend $S(u_1)$ ($= 2e_1$)

to a basis of $\ker S$:

add $w_1 = e_2 - e_3$

By the pg of 21.1, here is
a Jordan basis of $V = \mathbb{C}^4$:

$v_1, S(v_1), S^2(v_1), w_1$
Reverse

So basis is

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$$B = 2e_1, e_2 + e_3, e_4, e_2 - e_3$$

and

$$[S]_B = J_3(0) \oplus J_1(0).$$

PART C: Rings

22. Recap

Study rings $R = (R, +, \times)$,

commutative w/ additive identity 0,
multiplicative identity 1.

Ex. $\mathbb{Z}, \mathbb{Q}, \mathbb{R}, \mathbb{C}, \mathbb{Z}_n$

$$\mathbb{Z}[\sqrt{d}] = \{a + b\sqrt{d} : a, b \in \mathbb{Z}\}$$

($d \in \mathbb{Z}$ non-square)

(eg. $d = -1$, Gaussian integers $\mathbb{Z}[i]$).

Polynomial rings $F[x]$

(F a field)

Units: $u \in R$ is a unit
if $\exists v \in R$ s.t. $uv = 1$.

Units form a group $U(R)$
under mult.

$$\text{Ex. } U(\mathbb{Z}) = \{\pm 1\}.$$

Integral Domain (ID)

These satisfy extra axiom

$$ab = 0 \Rightarrow a = 0 \text{ or } b = 0.$$

Ex, All above are ID's

except for \mathbb{Z}_n for $n = r^2 s$,
non-prime: since then

$$[r][s] = [0].$$

Irreducibles Say $a \in R$ is

irreducible if

1) $a \neq 0$

2) $a \notin U(R)$

3) $a = bc$ ($b, c \in R$)

\Rightarrow b or c is a unit.

Ex, In \mathbb{Z} , irreducibles are the primes
In $F[x]$, they are the irreducible
polys.

Euclidean Domain (ED)

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An ID R is an ED if

\exists function $\delta: R \setminus \{0\} \rightarrow \mathbb{Z}_{\geq 0}$ st.

• $\delta(ab) \geq \delta(a) \quad \forall a, b \in R \setminus \{0\}$

• for any $a, b \in R$ with

$b \neq 0, \exists q, r \in R$ st.

$$a = qb + r$$

where either $r = 0$ or $\delta(r) < \delta(b)$.

Ex. 1) $R = \mathbb{Z}$, $\delta(a) = |a|$

2) $R = F[x]$, $\delta(f(x)) = \deg(f)$

3) $R = \mathbb{Z}[i]$, $\delta(a+ib) = a^2 + b^2$

$$4) R = \mathbb{Z}[\sqrt{-2}], \delta(a+b\sqrt{-2}) = a^2 + 2b^2.$$

(In fact for most values of d , $\mathbb{Z}[\sqrt{d}]$ is not an ED.)

Unique Factorization Domains (UFD)

Say R is a UFD if for any $a \in R$ with $a \neq 0$ and $a \notin U(R)$, the following hold:

1) \exists factorization

$$a = b_1 \dots b_r$$

where each b_i is irreducible

2) the b_i 's are unique, apart from mult. by \pm units.

Thm Every ED is a UFD.

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23.

~~Defn~~ Homomorphisms and ideals

Defn Let R, R' be rings.

Say $\phi: R \rightarrow R'$ is a homomorphism if

$$1) \phi(a+b) = \phi(a) + \phi(b) \quad \forall a, b \in R$$

$$2) \phi(ab) = \phi(a)\phi(b) \quad \forall a, b \in R$$

If ϕ is bijective, it is an isomorphism.

Ex. 1) Zero homom: $\phi(x) = 0 \quad \forall x \in \mathbb{Z}$

2) $\phi: \mathbb{Z} \rightarrow \mathbb{Z}_n$ defined by

$$\phi(x) = [x] \quad \forall x \in \mathbb{Z}.$$

3) $\phi: \mathbb{Z}[\sqrt{2}] \rightarrow \mathbb{Z}[\sqrt{2}]$,

$$\phi(a+b\sqrt{2}) = a-b\sqrt{2} \quad \forall a, b \in \mathbb{Z}.$$

Ex ϕ is an isomorphism.

4) $\phi: F[x] \rightarrow F$:

$$\phi(p(x)) = p(0) \quad \forall p(x) \in F[x]$$

eg. $\phi(x^2-3x+7) = 7$, is a homom.

Defn We say $I \leq R$ is an ideal if

1) $(I, +)$ is a subgroup

$$\mathcal{I}(\mathbb{R}, +)$$

2) $i \in I, r \in R \Rightarrow ir \in I$

(concisely: $\mathbb{I}R \subseteq I$).

Proposn (2) is much stronger than

closure under \times (subring)

Example Let $a \in R$ and define

$$I = \{ar : r \in R\} \\ = aR$$

Claim aR is an ideal of R .

If 1) $0 = a0 \in aR$

$$ar_1 + ar_2 = a(r_1 + r_2) \in aR$$

$$-ar = a(-r) \in aR$$

Hence $(aR, +)$ a subgroup of $(R, +)$

2) $(ar)s = a(rs) \in aR$. //

Defn We call aR an ideal

$$aR$$

the principal ideal generated by a .

Some texts denote aR by (a) .

Ex. $R = \mathbb{Z}, a=2$.

Principal ideal $2\mathbb{Z} = \{\text{even nos.}\}$.