### 2 M3-4-5 A16 Assessed Problems # 2

Due 2pm 1 Dec 2011

Please budget your time: Many of these problems are very easy, but some of the more interesting ones may become time consuming. So work steadily through them, don't wait until the last minute.

# Exercise 2.1 $\mathbb{R}^3$ -bracket for Maxwell-Bloch equations

The real-valued Maxwell-Bloch system for  $\mathbf{x} = (x_1, x_2, x_3)^T \in \mathbb{R}3$  is given by

$$\dot{x}_1 = x_2 \,, \quad \dot{x}_2 = x_1 x_3 \,, \quad \dot{x}_3 = -x_1 x_2 \,.$$

(a) Write this system in three-dimensional vector  $\mathbb{R}3$ -bracket notation as

$$\dot{\mathbf{x}} = \nabla H_1 \times \nabla H_2 \,,$$

where  $H_1$  and  $H_2$  are two conserved functions, one of whose level sets (let it be  $H_1$ ) may be taken as **circular cylinders** oriented along the  $x_1$ -direction and the other (let it be  $H_2$ ) whose level sets may be taken as **parabolic cylinders** oriented along the  $x_2$ -direction.

- (b) Restrict the equations and their  $\mathbb{R}3$  Poisson bracket to a level set of  $H_2$ . Show that the Poisson bracket on the parabolic cylinder  $H_2 = const$  is symplectic.
- (c) Derive the equation of motion on a level set of  $H_2$  and express them in the form of Newton's Law. Do they reduce to something familiar?
- (d) Identify steady solutions and determine which are unstable (saddle points) and which are stable (centers).

## Exercise 2.2 The fish: quadratically nonlinear oscillator

Consider the Hamiltonian dynamics on a symplectic manifold of a system comprising two real degrees of freedom, with real phase space variables  $(x, y, \theta, z)$ , symplectic form

$$\omega = dx \wedge dy + d\theta \wedge dz$$

and Hamiltonian

$$H = \frac{1}{2}y^2 + x\left(\frac{1}{3}x^2 - z\right) - \frac{2}{3}z^{3/2}$$

- (a) Write the canonical Poisson bracket for this system.
- (b) Write Hamilton's canonical equations for this system. Explain how to keep  $z \ge 0$ , so that H and  $\theta$  remain real.
- (c) At what values of x, y and H does the system have stationary points in the (x, y) plane?
- (d) Propose a strategy for solving these equations. In what order should they be solved?
- (e) Identify the constants of motion of this system and explain why they are conserved.
- (f) Compute the associated Hamiltonian vector field  $X_H$  and show that it satisfies

$$X_H \sqcup \omega = dH$$

- (g) Write the Poisson bracket that expresses the Hamiltonian vector field  $X_H$  as a divergenceless vector field in  $\mathbb{R}^3$  with coordinates  $\mathbf{x} = (x, y, z) \in \mathbb{R}^3$ . Explain why this Poisson bracket satisfies the Jacobi identity.
- (h) Identify the Casimir function for this  $\mathbb{R}^3$  bracket. Show explicitly that it satisfies the definition of a Casimir function.
- (i) Sketch a graph of the intersections of the level surfaces in  $\mathbb{R}^3$  of the Hamiltonian and Casimir function. Show the directions of flow along these intersections. Identify the locations and types of any relative equilibria at the tangent points of these surfaces.
- (j) Linearise around the relative equilibria on a level set of the Casimir (z) and compute its eigenvalues.
- (k) If you found a hyperbolic equilibrium point in the previous part connected to itself by a homoclinic orbit, then reduce the equation for the homoclinic orbit to an indefinite integral expression.

# Exercise 2.3 2D coupled oscillators

Consider the 2D oscillator Hamiltonian  $H: \mathbb{C}^2 \to \mathbb{R}$ , with complex 2-vector  $\mathbf{a} = (a_1, a_2) \in \mathbb{C}^2$  and constant frequencies  $\omega_i$ ,

$$H = \frac{1}{2} \sum_{j=1}^{2} \omega_j |a_j|^2 = \frac{1}{4} (\omega_1 + \omega_2) (|a_1|^2 + |a_2|^2) + \frac{1}{4} (\omega_1 - \omega_2) (|a_1|^2 - |a_2|^2).$$

(a) Compute its canonical Hamiltonian dynamics with

$$\{a_j, a_k^*\} = -2i\delta_{jk}.$$

Explain why this is the sum of a 1:1 resonant oscillator and a 1:-1 oscillator.

(b) Find the transformations generated by X, Y, Z, R on  $a_1, a_2$ , where

$$R = |a_1|^2 + |a_2|^2,$$

$$Z = |a_1|^2 - |a_2|^2,$$

$$X - iY = 2a_1 a_2^*.$$

Express these infinitesimal transformations as matrix operations and identify their corresponding finite transformations.

(c) For the starting Hamiltonian,

$$H = \frac{\omega_1}{2} (R + Z) + \frac{\omega_2}{2} (R - Z)$$
  
=  $\frac{1}{2} (\omega_1 + \omega_2) R + \frac{1}{2} (\omega_1 - \omega_2) Z$ ,

write the equations  $\dot{X}, \dot{Y}, \dot{Z}, \dot{R}$  for the  $S^1$  invariants X, Y, Z, R of the 1:1 resonance.

Write these equations in vector form, with  $\mathbf{X} = (X, Y, Z)^T$ , and describe this motion in terms of level sets of the Poincaré sphere and the Hamiltonian H.

# Exercise 2.4 Matrix rigid body equations & cotangent lift momentum maps

(a) Let the Lie group SO(n) act on itself with infinitesimal transformation

$$\Phi_{\Xi}(Q) = Q\Xi \quad \text{for} \quad Q \in SO(n) \quad \text{and} \quad \Xi = -\Xi^T \in \mathfrak{so}(n)$$

Compute the cotangent lift (CL) momentum map for this action and its CL infinitesimal action on  $T^*SO(n)$ .

(b) Compute the variations in Hamilton's principle  $\delta S = 0$  with Clebsch-constrained action integral

$$S(\Omega, Q, P) = \int_{a}^{b} l(\Omega) + \operatorname{tr}\left(P^{T}\left(\dot{Q} - Q\Omega\right)\right) dt.$$

Discuss the relation between these variational equations and the equations for the infinitesimal Lie algebra actions associated with CL momentum maps.

(c) Show that the Clebsch-constrained Hamilton's principle implies that  $M=\partial l/\partial\Omega$  satisfies the Euler-Poincaré equation

$$\frac{dM}{dt} = \mathrm{ad}_{\Omega}^* M = -\left[\Omega, M\right].$$

## Exercise 2.5 2:1 resonance

The Hamiltonian  $\mathbb{C}^2 \to \mathbb{R}$  for a certain 2:1 resonance is given by

$$H = \frac{1}{2}|a_1|^2 - |a_2|^2 + \frac{1}{2}\operatorname{Im}(a_1^{*2}a_2),$$

in terms of canonical variables  $(a_1, a_1^*, a_2, a_2^*) \in \mathbb{C}^2$  whose Poisson bracket relation

$$\{a_j, a_k^*\} = -2i\delta_{jk}, \quad for \quad j, k = 1, 2,$$

is invariant under the 2:1 resonance  $S^1$  transformation

$$a_1 \to e^{i\phi}$$
 and  $a_2 \to e^{2i\phi}$ .

- (a) Write the motion equations in terms of the canonical variables  $(a_1, a_1^*, a_2, a_2^*) \in \mathbb{C}^2$ .
- (b) Introduce the orbit map  $\mathbb{C}^2 \to \mathbb{R}^4$

$$\pi: (a_1, a_1^*, a_2, a_2^*) \to \{X, Y, Z, R)\}$$

and transform the Hamiltonian H on  $\mathbb{C}^2$  to new variables  $X,Y,Z,R\in\mathbb{R}^4$  given by

$$R = \frac{1}{2}|a_1|^2 + |a_2|^2,$$

$$Z = \frac{1}{2}|a_1|^2 - |a_2|^2,$$

$$X - iY = 2a_1^{*2}a_2,$$

that are invariant under the 2:1 resonance  $S^1$  transformation.

- (c) Show that these variables are functionally dependent, because they satisfy a cubic algebraic relation C(X,Y,Z,R)=0.
- (d) Use the orbit map  $\pi: \mathbb{C}^2 \to \mathbb{R}^4$  to make a table of Poisson brackets among the four quadratic 2:1 resonance  $S^1$ -invariant variables  $X, Y, Z, R \in \mathbb{R}^4$ .
- (e) Show that both R and the cubic algebraic relation C(X, Y, Z, R) = 0 are Casimirs for these Poisson brackets.
- (f) Write the Hamiltonian, Poisson bracket and equations of motion in terms of the remaining variables  $\mathbf{X} = (X, Y, Z)^T \in \mathbb{R}^3$ .
- (g) Describe this motion in terms of level sets of the Hamiltonian H and the orbit manifold for the 2:1 resonance, given by C(X,Y,Z,R)=0.
- (h) Restrict the dynamics to a level set of the Hamiltonian and show that it reduces there to the equation of motion for a point particle in a cubic potential. Explain its geometrical meaning.
- (i) Compute the geometric and dynamic phases for any closed orbit on a level set of H.

## Exercise 2.6 Three-wave equations

The three-wave equations of motion take the symmetric form

$$i\dot{A} = B^*C$$
,  $i\dot{B} = CA^*$ ,  $i\dot{C} = AB$ , for  $(A, B, C) \in \mathbb{C} \times \mathbb{C} \times \mathbb{C} \simeq \mathbb{C}^3$ .

- (a) Write these equations as a Hamiltonian system. How many degrees of freedom does it have?
- (b) Find two additional constants of motion for it, besides the Hamiltonian.
- (c) Use the Poisson bracket to identify the symmetries of the Hamiltonian associated with the two additional constants of motion, by computing their Hamiltonian vector fields and integrating their characteristic equations.
- (d) Set:

$$A = |A| \exp(i\xi)$$
,  $B = |B| \exp(i\eta)$ ,  $C = Z \exp(i(\xi + \eta))$ .

Determine whether this transformation is canonical.

(e) Express the three-wave problem entirely in terms of the variable  $Z = |Z|e^{i\zeta}$ , reduce the motion to a single equation for |Z| then reconstruct the full solution as,

$$A = |A| \exp(i\xi)$$
,  $B = |B| \exp(i\eta)$ ,  $C = |Z| \exp(i(\xi + \eta + \zeta))$ .

That is, reduce the motion to a single equation for |Z| then write the various differential equations for |A|,  $\xi$ , |B|,  $\eta$  and  $\eta$ .