

# Fourier Series Methods for Numerical Conformal Mapping of Smooth Domains

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Conformal Geometry in Mapping, Imaging, and Sensing

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# Outline

## 1 Introduction

- Some background
- Numerical preview and gallery

## 2 Fourier series methods

- Fornberg's method for the disk (1980)
  - Analyticity conditions
  - Linearization
  - Discretization by  $N$ -pt. trig. interp.
- Fornberg-like method for the annulus (1998)
- Multiply connected Fornberg (bounded case, 2009)

## 3 Remarks and extra details

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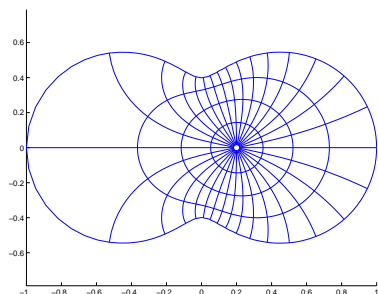
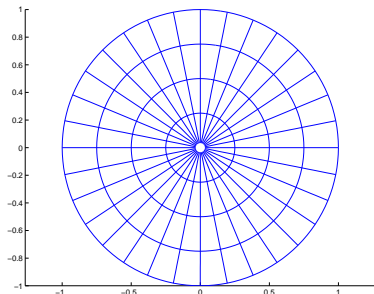
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# Collaborators

Colleagues: Alan Elcrat (WSU) and John Pfaltzgraff (UNC Chapel Hill)

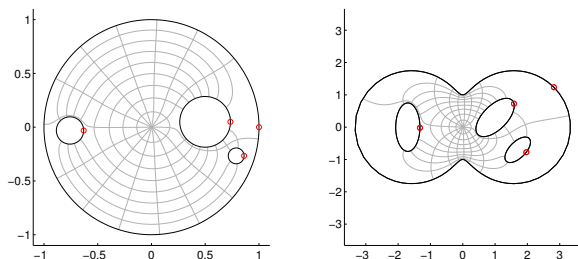
MS/PhD students: Mark Horn, Nouredine Benchama, Lianju (Julian) Wang, and **Everett Kropf**

# Conformal map $w = f(z)$ from disk to target domain



**Figure:** Fornberg (Fourier series) map from **unit disk** to **interior of an inverted ellipse** using **64** Fourier points.  $f'(z) \neq 0$ , so locally  $f(a+h) \approx f(a) + f'(a)h$  and  $f$  maps a small circle near  $z = a$  to a circle near  $f(a)$  magnified by  $|f'(a)|$  and rotated by  $\arg f'(a)$ . Therefore curves intersecting at angle  $\theta$  at  $a$  will be mapped to curves intersecting at angle  $\theta$  at  $f(a)$  and the map is *angle-preserving* or *conformal*. Existence and uniqueness given by **Riemann Mapping Theorem** with  $f(0)$  and  $f(1)$  fixed.

# Interior mult. conn. case—Kropf's MS thesis (2009)



**Figure:** Outer circle is unit circle. Map normalization fixes  $f(0)$  and  $f(1)$ .  $m = 4$  **boundary correspondences and centers and radii** of inner circles (unique “**conformal moduli**”) must be computed.

## Boundary correspondence

The boundary  $\Gamma$  of  $\Omega$  is parametrized by  $S$  (e.g., arclength or polar angle),  $\Gamma : \gamma(S), 0 \leq S \leq L, \gamma(0) = \gamma(L)$ . If  $S = S(\theta)$  or its inverse  $\theta(S) = \arg f^{-1}(\gamma(S))$  is known, then the map is known for  $z \in D$  or  $w \in \Omega$  by the Cauchy Integral Formula,

$$w = f(z) = \frac{1}{2\pi i} \int_C \frac{\gamma(S(\theta))}{\zeta - z} d\zeta(\theta)$$

or

$$z = f^{-1}(w) = \frac{1}{2\pi i} \int_{\Gamma} \frac{e^{i\theta(S)}}{\gamma(S) - w} d\gamma(S).$$

## Two classes of “traditional” methods

1. Find  $S = S(\theta)$  such that  $f(e^{i\theta}) = \gamma(S(\theta))$ . We will discuss this case. These methods solve a nonlinear integral equation for  $S(\theta)$  by linearly convergent methods of successive approximation (Picard-like iteration) such as Theodorsen’s method, or quadratically convergent Newton-like methods such as Fornberg’s or Wegmann’s methods. Cost:  $O(N \log N)$  with FFTs.
2. Find  $\theta = \theta(S)$  such that  $f^{-1}(\gamma(S)) = e^{i\theta(S)}$ . These methods solve linear integral equations arising from potential theory for  $\theta(S)$  or  $\theta'(S)$ . Cost:  $O(N^2)$  operation counts, but can handle more highly distorted regions.



MANY other methods exist, as we see at this meeting, based on ideas from computational geometry, circle packing, Riemann-Hilbert problems, orthogonalization, compositions of explicit maps (Grassmann, Marshall),...

## A few general references

- [1.] T. A. Driscoll and L. N. Trefethen, *Schwarz-Christoffel mapping*, Cambridge U. Press, 2002.
- [2.] D. Gaier, *Konstruktive Methoden der konformen Abbildung*, Springer, 1964.
- [3.] X. D. Gu and S.-T. Yau, *Computational Conformal Geometry*, International Press, 2008.
- [4.] P. Henrici, *Applied and Computational Complex Analysis, Vol. 3*, Wiley, 1986.
- [5.] K. Stephenson, *Introduction to Circle Packing*, Cambridge, 2005.
- [6.] R. Wegmann, *Methods for Numerical Conformal Mapping*, survey article in Handbook of Complex Analysis: Geometric Function Theory, Vol. 2, R. Kühnau, ed., Elsevier, 2005, pp. 351–477.

# Key idea for this talk: Taylor/Laurent series = Fourier series

For  $|z| < |\zeta| = 1$ ,  $\zeta = e^{i\theta}$ ,  $d\zeta = ie^{i\theta} d\theta$

$$\begin{aligned}
 f(z) &= \frac{1}{2\pi i} \int_{|\zeta|=1} \frac{\gamma(S(\theta))}{\zeta - z} d\zeta \\
 &= \frac{1}{2\pi i} \int_{|\zeta|=1} \gamma(S(\theta)) \left( 1 + \frac{z}{\zeta} + \left(\frac{z}{\zeta}\right)^2 + \dots \right) \frac{d\zeta}{\zeta} \\
 &= \frac{1}{2\pi} \int_0^{2\pi} \gamma(S(\theta)) (1 + ze^{-i\theta} + z^2 e^{-2i\theta} + \dots) d\theta \\
 &= \sum_{k=0}^{\infty} \left( \frac{1}{2\pi} \int_0^{2\pi} \gamma(S(\theta)) e^{-ik\theta} d\theta \right) z^k \\
 &= \sum_{k=0}^{\infty} a_k z^k,
 \end{aligned}$$

Taylor coeff. = Fourier coeff.  $a_k := \frac{1}{2\pi} \int_0^{2\pi} \gamma(S(\theta)) e^{-ik\theta} d\theta$ .

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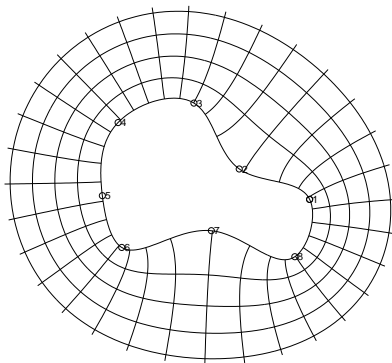


Figure: Fornberg map from exterior of unit disk to exterior of spline

# Simply-connected case: crowding=large distortions=Ill-conditioning

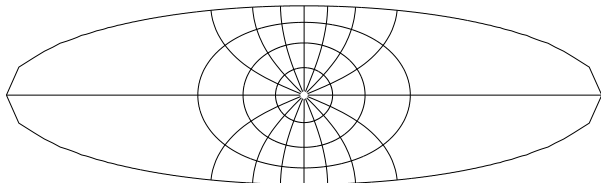
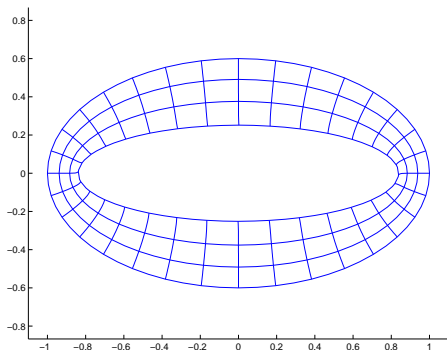


Figure: Fornberg (Fourier series) map from **unit disk** to **interior of ellipse** using **1024** Fourier points.

# Map from annulus—D. and Pfaltzgraff (1998)



**Figure:** Doubly connected Fornberg maps annulus  $\rho < |z| < 1$  to domain between two ellipses  $\alpha = .3, .6$  with  $N = 64$ . Normalization fixes one boundary point  $f(1)$  to fix rotation of annulus. The inner and outer **boundary correspondences**  $S = S_1(\theta)$  and  $S = S_2(\theta)$  along with the unique  $\rho (=1/\text{conformal modulus})$  must be computed numerically.

# Exterior mult. conn. case—Benchama's PhD thesis (2003)

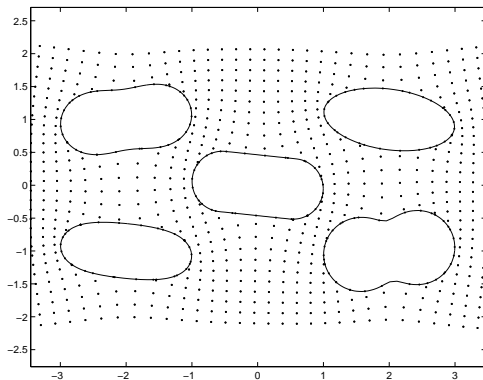
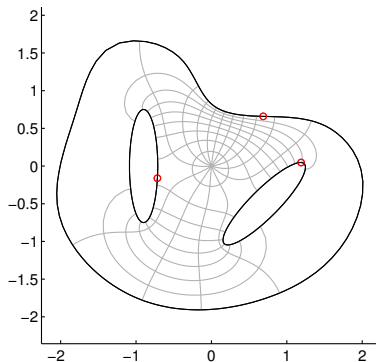
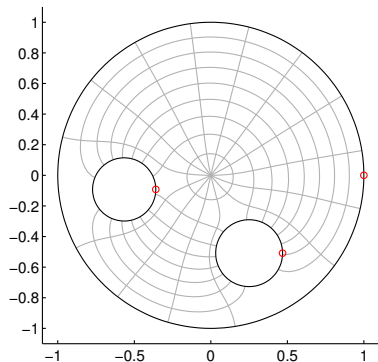


Figure: Fornberg map to the exterior of five curves.

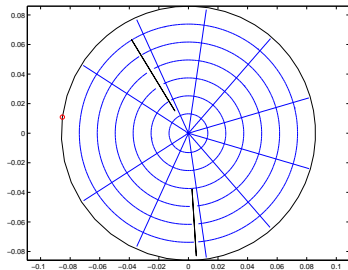
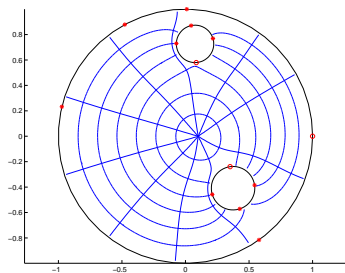


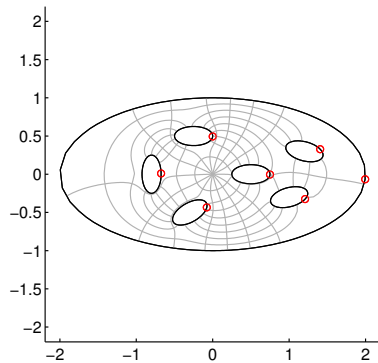
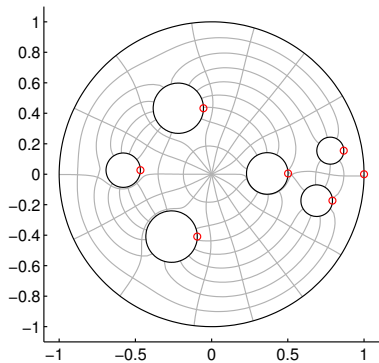
# Interior mult. conn. case—Kropf's MS thesis (2009)



- A target region (on the right) with an outer spline boundary which is parametrized by arclength.

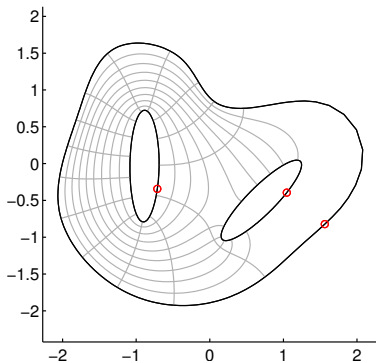
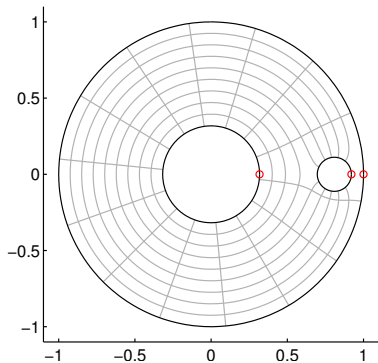
# Radial slit map from Kropf's PhD thesis (2012)





- A target region with  $m = 7$ .

# Numerical Example



- Annulus with circular holes as a computational domain.

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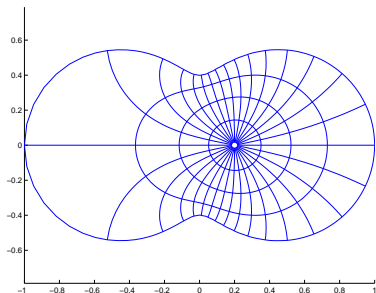
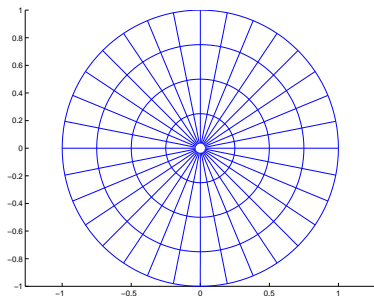


Figure: Fornberg (Fourier series) map from **unit disk** to **interior of an inverted ellipse** using **64** Fourier points. Normalization fixes three real parameters:  $f(0)$  fixed and  $f(1)$  fixed.

## Some useful linear operators

For  $h = h(\theta)$ ,  $2\pi$ -periodic,  $h(\theta) = \sum_{k=-\infty}^{\infty} c_k e^{ik\theta}$

$$Jh(\theta) := \frac{1}{2\pi} \int_0^{2\pi} h(\theta) d\theta = c_0$$

$$P_+ h(\theta) := \sum_{k=1}^{\infty} c_k e^{ik\theta}$$

$$P_- h(\theta) := \sum_{k=-\infty}^0 c_k e^{ik\theta}$$

Note that  $P_{\pm}^2 = P_{\pm}$  are *projection operators* onto subspaces of  $L^2[0, 2\pi]$  whose nonpositive/positive indexed Fourier coefficients 0. Also note

$$P_+ h = \frac{1}{2}(I + iK - J)h,$$

$$P_- h = \frac{1}{2}(I - iK + J)h.$$





# Condition for analytic extension of boundary values

## Theorem

A function  $h \in Lip(\Gamma)$  can be continued analytically into  $D^+$  (i.e.,  $f(t) = h(t), t \in \Gamma$ ) if and only if

$$f(z) := \frac{1}{2\pi i} \int_{\Gamma} \frac{h(t)}{t-z} dt = 0, \quad z \in D^-,$$

or, equivalently, if

$$\frac{1}{2\pi i} \int_{\Gamma} t^n h(t) dt = 0, \quad n = 0, 1, 2, \dots$$

## Proof.

Cauchy Integral Theorem and Sokhotskyi jump relations,  $f^+ - f^- = h$ ; see, e.g., Henrici, ACCA, v. 3, Muskhelishvili, SIE.

## Condition for unit $D$ =disk

### Theorem

*A function  $f \in \text{Lip}(C)$  on the boundary  $C$  of the unit disk extends to an analytic function in the interior of the disk with  $f(0) = 0$  if and only if*

$$P_- f(e^{i\theta}) = 0. \quad (1)$$

That is, negative indexed coefficients are 0.

## Linearization

Given the  $k$ th Newton iterate  $S = S^k(\theta)$ , find correction  $U^k(\theta)$ , real, such that

$$f(e^{i\theta}) = \gamma(S^k(\theta) + U^k(\theta)) \approx \xi(\theta) + e^{i\beta(\theta)} U(\theta)$$

extends analytically to the interior of the unit disk with  $f(0) = 0$ , where  $\xi(\theta) = \gamma(S^k(\theta))$ ,  $\beta(\theta) = \arg \gamma'(S^k(\theta))$ , and  $U(\theta) := |\gamma'(S^k(\theta))| U^k(\theta)$  extends analytically to the interior of the unit disk with  $f(0) = 0$ . The analyticity condition

$$2P_- f = (I - iK + J)f = 0$$

implies that

$$(I - iK + J)e^{i\beta(\theta)} U(\theta) = -2P_- \xi(\theta).$$

$U$  real gives

$$(I + R)U = r$$

where  $R = \operatorname{Re}(e^{-i\beta}(J - iK)e^{i\beta})$  and  $r = -\operatorname{Re}(e^{-i\beta}(I - iK + J)\xi)$ .

# $R$ is a compact operator (Widlund, Wegmann)

$$RU(\theta) := \frac{1}{2\pi} \int_0^{2\pi} \frac{\sin\left(\beta(\phi) - \beta(\theta) + \frac{\theta - \phi}{2}\right)}{\sin\left(\frac{\theta - \phi}{2}\right)} U(\phi) d\phi,$$

and for  $\gamma$  sufficiently smooth  $R^{in}$  is a symmetric, compact operator on  $L^2$ .

## Discretization by $N$ -pt. trig. interp.

With  $E = \text{diag}_j(e^{j\beta(\theta_j)})$ ,  $j = 0, 1, \dots, N-1$ , discretization gives

$$A\underline{U} = (I_N + R_N)\underline{U} = \underline{r}.$$

where the matrix

$$I_N + R_N = \frac{2}{N} \text{Re}(E^H F^H P_N F E)$$

(with  $P_N := \text{diag}[1, 0, \dots, 0, 1, \dots, 1]$ ) is symmetric and pos.(semi)def. with eigenvalues well-grouped around 1 and conjugate gradient converges superlinearly.

Matrix-vector multiplications costs  $O(N \log N)$  with FFT.

The *Newton update* is given by

$$\underline{S}^{(k+1)} = \underline{S}^{(k)} + \underline{U}^{(k)},$$

with  $U_0 = 0$  set to fix a boundary point

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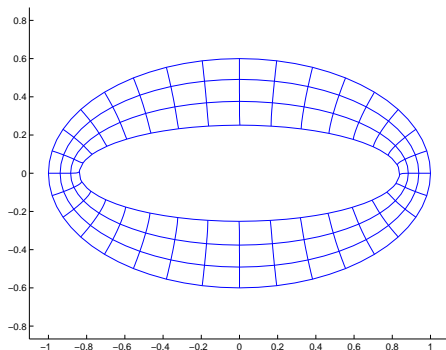
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## Analyticity conditions

Let  $C_1$  and  $C_2$  denote the outer and inner boundaries, respectively, of the annulus  $\rho < |z| < 1$ , and put  $C = C_1 - C_2$ .

### Theorem

A function  $h \in Lip(C)$  extends analytically to the annulus  $\rho < |z| < 1$  if and only if

$$\int_{C_1} h(z)z^k dz = \int_{C_2} h(z)z^k dz, \quad k \in \mathbf{Z}.$$

If we let

$$h(e^{i\theta}) = \sum_{k=-\infty}^{\infty} a_k e^{ik\theta} \quad h(\rho e^{i\theta}) = \sum_{k=-\infty}^{\infty} b_k e^{ik\theta}$$

then the above condition becomes  $\rho^k a_k = b_k$ ,  $k \in \mathbf{Z}$  or (to prevent overflow)

$$\rho^k a_k = b_k, \quad a_{-k} = \rho^k b_{-k}, \quad k = 0, 1, 2, \dots$$



# Mapping problem

Target region  $\Omega$  bounded by two smooth curves  $\Gamma_1 : \gamma_1(S_1)$  and  $\Gamma_2 : \gamma_2(S_2)$ .

**Problem:** Find the *boundary correspondences*  $S_1(\theta)$  and  $S_2(\theta)$  and the *conformal modulus*  $\rho$  such that  $f(z)$  is analytic in the annulus  $\rho < |z| < 1$  and  $f(e^{i\theta}) = \gamma_1(S_1(\theta))$  and  $f(\rho e^{i\theta}) = \gamma_2(S_2(\theta))$ .

## Linearization for Newton-like method

At each Newton step we want to compute corrections  $U_1(\theta)$ ,  $U_2(\theta)$ , and  $\delta\rho$  to  $S_1(\theta)$ ,  $S_2(\theta)$ , and  $\rho$ . With  $S_j$  arclength,  $\beta_j(\theta) := \arg \gamma_j'(S_j(\theta))$ ,  $\xi_j(\theta) := \gamma_j(S_j(\theta))$ ,  $j = 1, 2$ ,  $\zeta(\theta) := f'(\rho e^{i\theta})e^{i\theta} = -ie^{i\beta_2(\theta)} dS_2(\theta)/d\theta/\rho$ , as in [LM] we **linearize** about  $S_1$ ,  $S_2$ , and  $\rho$ ,

$$\begin{aligned}\gamma_j(S_j(\theta) + U_j(\theta)) &\approx \gamma_j(S_j(\theta)) + \gamma_j'(S_j(\theta))U_j(\theta), \quad j = 1, 2, \\ f((\rho + \delta\rho)e^{i\theta}) &\approx f(\rho e^{i\theta}) + f'(\rho e^{i\theta})\delta\rho e^{i\theta}\end{aligned}$$

giving

$$\begin{aligned}f(e^{i\theta}) &\approx \xi_1(\theta) + e^{i\beta_1(\theta)}U_1(\theta) \\ f(\rho e^{i\theta}) &\approx \xi_2(\theta) + e^{i\beta_2(\theta)}U_2(\theta) - \zeta(\theta)\delta\rho.\end{aligned}$$

We find  $U_1$ ,  $U_2$ ,  $\delta\rho$  to force these BVs to satisfy the **analyticity conditions** for the annulus.

## Linear system

Letting  $a_k$  and  $b_k$  now denote the  $N$  discrete Fourier coefficients and using the  $N$ -periodicity  $a_{k+N} = a_k$ , we have with  $N = 2M$

$$\underline{a} = (a_0, a_1, \dots, a_M, a_{M+1}, \dots, a_{N-1})^T = (a_0, a_1, \dots, a_M, a_{-M+1}, \dots, a_{-1})^T$$

$\underline{b}$  is defined similarly. Next define the  $N \times N$  matrices  $P_1 = \text{diag}(1, \rho, \dots, \rho^{M-1}, 1, \dots, 1)$  and  $P_2 = -\text{diag}(1, \dots, 1, 1, \rho^{M-1}, \dots, \rho)$ . If we set  $a_M = b_M$  as in [Fo2, eq. 6], we write the discrete form of our analyticity conditions as

$$(29) \quad P_1 \underline{a} + P_2 \underline{b} = 0.$$

## Linear system

With  $E_j := \text{diag}_{l=0, \dots, N-1}(e^{i\beta_j(\theta_l)})$ ,  $j = 1, 2$ , our discrete linearizations become

$$(30) \quad N\underline{a} = F\underline{\xi}_1 + FE_1\underline{U}_1$$

$$(31) \quad N\underline{b} = F\underline{\xi}_2 + FE_2\underline{U}_2 - F\underline{\zeta}\delta\rho.$$

Substituting these linearizations into the discrete analyticity conditions gives our linear system for  $\underline{U}_1$ ,  $\underline{U}_2$ , and  $\delta\rho$ ,

$$(C \underline{w})\underline{U} = P_1FE_1\underline{U}_1 + P_2FE_2\underline{U}_2 - P_2F\underline{\zeta}\delta\rho = -P_1F\underline{\xi}_1 - P_2F\underline{\xi}_2 =: \underline{c}.$$

where  $C = (P_1FE_1 \ P_2FE_2)$  is a complex  $N \times 2N$  matrix,  $\underline{w} = -P_2F\underline{\zeta}$  is a complex  $N$ -vector, and

$$\underline{U} = \begin{bmatrix} \underline{U}_1 \\ \underline{U}_2 \\ \delta\rho \end{bmatrix}.$$

We have a system of  $N$  complex equations in  $2N + 1$  real unknowns,  $\underline{U}$ . To satisfy the normalization  $f(1) = \gamma_1(0)$ , we add the equation  $\underline{q}^T \underline{U} = U_0 = \delta := 0$ , where  $\underline{q}^T = (1, 0, \dots, 0)^T$  is a  $2N + 1$ -vector. We write

$$D = \begin{bmatrix} C & w \\ \sqrt{N} & \underline{q}^T/2 \end{bmatrix}, \quad \underline{g} := \begin{bmatrix} c \\ \delta \end{bmatrix}.$$

and our system now becomes

$$D\underline{U} = \underline{g},$$

a system of  $N$  complex equations and 1 real equation for the  $2N + 1$  real unknowns,  $\underline{U}$ . Using the normal equations and  $\underline{U}$  real, we have

$$A\underline{U} = \frac{2}{N} \operatorname{Re}(D^H D) \underline{U} = \underline{r} := \frac{2}{N} \operatorname{Re}(D^H \underline{g}).$$

As in the simply connected case, we solve the system by the conjugate gradient method using FFTs.

The matrix  $A$  is a discretization of the identity plus a compact operator as in the disk case. We have the following  $2N + 1 \times 2N + 1$ -matrix

$$A = \frac{2}{N} \operatorname{Re}(D^H D) = \begin{bmatrix} A_{11} & A_{12} & \underline{w}_1 \\ A_{12}^T & A_{22} & \underline{w}_2 \\ \underline{w}_1^H & \underline{w}_2^H & 2\underline{w}^H \underline{w} / N \end{bmatrix} + \frac{1}{2} \underline{q} \underline{q}^T$$

where  $A_{ij} = \frac{2}{N} \operatorname{Re}(E_i^H F^H P_i P_j F E_j)$  and  $\underline{w}_i = \frac{2}{N} \operatorname{Re}(E_i^H F^H P_i \underline{w})$ ,  $i, j = 1, 2$ . Now it is easy to see that  $A_{11}$  is a (low rank perturbation of) the discretization of

$$2\operatorname{Re}(e^{-i\beta_1} (P_- + l_1 *) e^{i\beta_1}) = I + R_1 + C_1$$

with  $N$ -point trigonometric interpolation where

$R_1 = \operatorname{Re}(e^{-i\beta_1} (J - iK) e^{i\beta_1})$  is compact,  $*$  is convolution,

$l_1(\theta) = \rho^2 e^{i\theta} / (1 - \rho^2 e^{i\theta}) = \sum_{k=1}^{\infty} \rho^{2k} e^{ik\theta}$ , and

$C_1 = 2\operatorname{Re}(e^{-i\beta_1} l_1 * (e^{i\beta_1}))$  is the product of bounded operators and a convolution and is, hence, compact.

# Newton update

$$\underline{s}_1^{(k+1)} = \underline{s}_1^{(k)} + \underline{U}_1^{(k)}$$

$$\underline{s}_2^{(k+1)} = \underline{s}_2^{(k)} + \underline{U}_2^{(k)}$$

$$\rho^{(k+1)} = \rho^{(k)} + \delta\rho^{(k)}.$$

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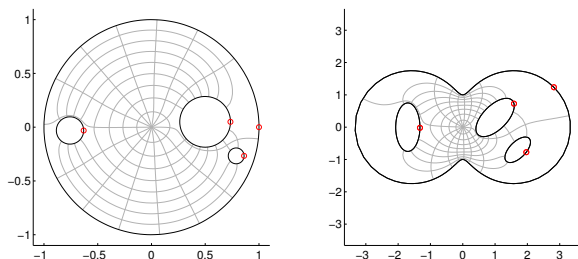
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  - Discretization by  $N$ -pt. trig. interp.
- Fornberg-like method for the annulus (1998)
- **Multiply connected Fornberg (bounded case, 2009)**

## 3 Remarks and extra details

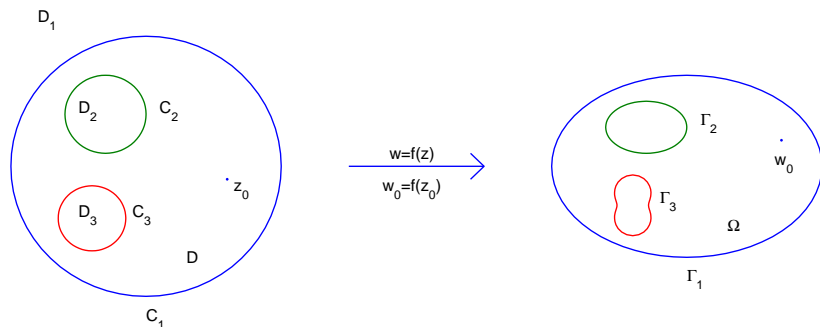


## Interior mult. conn. case—Kropf's MS thesis (2009)



**Figure:** Outer circle is unit circle. Map normalization fixes  $f(0)$  and  $f(1)$ .  $m = 4$  **boundary correspondences and centers and radii** of inner circles (unique “**conformal moduli**”) must be computed.

# Computational Goal



- The goal is to compute the conformal map  $f : D \rightarrow \Omega$ .
- To do this we must calculate
  - 1 the centers  $c_\nu$  and radii  $\rho_\nu$  of the circles  $C_\nu$ ,  $2 \leq \nu \leq m$ , and
  - 2 the boundary correspondences  $S_\nu(\theta)$ , where  $0 \leq \theta \leq 2\pi$ ,
 such that  $f(c_\nu + \rho_\nu e^{i\theta}) = \gamma_\nu(S_\nu(\theta))$ ,  $1 \leq \nu \leq m$ .

# Form of the Map

## Theorem

*The conformal map described above has the series representation*

$$f(z) = \sum_{j=0}^{\infty} a_{1,j} z^j + \sum_{\nu=2}^m \sum_{j=1}^{\infty} a_{\nu,-j} \left( \frac{\rho_{\nu}}{z - c_{\nu}} \right)^j,$$

*where for  $1 \leq \nu \leq m$  and  $j > 0$  the Fourier coefficients  $a_{\nu,j}$  are defined*

$$a_{\nu,j} := \frac{1}{2\pi} \int_0^{2\pi} f(c_{\nu} + \rho_{\nu} e^{i\theta}) e^{-ij\theta} d\theta.$$

# Analytic Continuation

## Theorem

*Let  $C$  be a positively oriented, Lipschitz continuous curve with  $D$  the region bounded by  $C$  and  $D^-$  the complement of  $D \cup C$ . A function  $f \in \text{Lip}(C)$  can be continued analytically into  $D$  if and only if*

$$\frac{1}{2\pi i} \int_C \frac{f(\zeta)}{\zeta - z} d\zeta = 0, \quad \forall z \in D^-.$$

Now applied to multiply connected circle domain  $D$ .

# Analyticity Conditions

## Theorem

A function  $f \in \text{Lip}(C)$  extends analytically into  $D$  if and only if for all  $k \geq 0$

$$a_{1,-(k+1)} - \sum_{\nu=2}^m \sum_{j=0}^k \binom{k}{j} \rho_{\nu}^{j+1} c_{\nu}^{k-j} a_{\nu,-(j+1)} = 0$$

and

$$\sum_{j=0}^{\infty} B_{k+1,j} \rho_{\ell}^k c_{\ell}^j a_{1,k+j} - a_{\ell,k} - \sum_{\substack{\nu=2 \\ \nu \neq \ell}}^m \sum_{j=0}^{\infty} \frac{\rho_{\ell}^k}{(c_{\nu} - c_{\ell})^{k+1}} B_{k+1,j} \frac{\rho_{\nu}^{j+1}}{(c_{\ell} - c_{\nu})^j} a_{\nu,-(j+1)} = 0.$$

## Note on Analyticity Conditions

For the analyticity conditions we need to define some binomial coefficients.

### Definition

For  $k > 0$  and  $x, y \in \mathbb{C}$ ,

$$(x + y)^k = \sum_{j=0}^k \binom{k}{j} x^{k-j} y^j \quad \text{where} \quad \binom{k}{j} := \frac{k!}{j!(k-j)!}.$$

### Definition

For  $k > 0$  and  $|z| < 1$ ,

$$\frac{1}{(1-z)^k} = \sum_{j=0}^{\infty} B_{k,j} z^j \quad \text{where} \quad B_{k,j} := \frac{k(k+1)\cdots(k+j-1)}{j!}.$$

# Note on Proof of Analyticity Conditions

The proof involves

- 1 applying the above analytic continuation Theorem for an arbitrary point  $z$  in each  $D_1, \dots, D_m$ ,
- 2 expanding the function in the appropriate Laurent series, and
- 3 setting the resulting series equal to 0.

# Proof of Analyticity Conditions

(Outside  $C_1$ )

## Proof.

For  $z$  in  $D_1$  we have  $|z| > 1$  and  $|\zeta|/|z| < 1$  for  $\zeta$  on any  $C_1, \dots, C_m$ , thus

$$\begin{aligned} \frac{1}{2\pi i} \int_C \frac{f(\zeta)}{\zeta - z} d\zeta &= -\frac{1}{2\pi i} \int_C f(\zeta) \frac{1}{z} \sum_{k=0}^{\infty} \left(\frac{\zeta}{z}\right)^k d\zeta \\ &= -\sum_{k=0}^{\infty} z^{-k-1} \frac{1}{2\pi i} \int_C f(\zeta) \zeta^k d\zeta = 0. \end{aligned}$$

The last integral on the RHS must be zero for all  $k \geq 0$ .



# Proof of Analyticity Conditions

(Outside  $C_1$ )

Proof.

$$\begin{aligned}
 0 &= \frac{1}{2\pi i} \int_C f(\zeta) \zeta^k d\zeta = \frac{1}{2\pi i} \int_{C_1} f(\zeta) \zeta^k d\zeta - \sum_{\nu=2}^m \frac{1}{2\pi i} \int_{C_\nu} f(\zeta) \zeta^k d\zeta \\
 &= \frac{1}{2\pi} \int_0^{2\pi} f(e^{i\theta}) e^{i(k+1)\theta} d\theta \quad (\text{Note : } \zeta^k = (c_\nu + \rho_\nu e^{i\theta})^k \\
 &\quad - \sum_{\nu=2}^m \sum_{j=0}^k \binom{k}{j} \rho_\nu^{j+1} c_\nu^{k-j} \frac{1}{2\pi} \int_0^{2\pi} f(c_\nu + \rho_\nu e^{i\theta}) e^{i(j+1)\theta} d\theta \\
 &= a_{1, -(k+1)} - \sum_{\nu=2}^m \sum_{j=0}^k \binom{k}{j} \rho_\nu^{j+1} c_\nu^{k-j} a_{\nu, -(j+1)}.
 \end{aligned}$$

# Map Normalization

- The map is normalized by specifying three real conditions:

- ▶  $f(1) = \gamma_1(0)$  and
- ▶

$$w_0 = f(z_0) = \sum_{k=0}^{\infty} a_{1,k} z_0^k + \sum_{\nu=2}^m \sum_{k=1}^{\infty} a_{\nu,-k} \left( \frac{\rho_{\nu}}{z_0 - c_{\nu}} \right)^k .$$

## Linearization

We now write  $f(\mathbf{c}_\nu + \rho_\nu \mathbf{e}^{i\theta}) = \gamma_\nu(\mathbf{S}_\nu(\theta))$  as a linear problem.

- For an initial guess  $\mathbf{S}_\nu(\theta)$  and  $2\pi$  periodic correction  $U_\nu(\theta)$ ,

$$\gamma_\nu(\mathbf{S}_\nu(\theta) + U_\nu(\theta)) \approx \gamma_\nu(\mathbf{S}_\nu(\theta)) + \gamma'_\nu(\mathbf{S}_\nu(\theta))U_\nu(\theta).$$

- For an initial guess of  $\mathbf{c}_\nu$  and  $\rho_\nu$  with corrections  $\delta\mathbf{c}_\nu$  and  $\delta\rho_\nu$ ,

$$\begin{aligned} (f + \delta f)(\mathbf{c}_\nu + \delta\mathbf{c}_\nu + (\rho_\nu + \delta\rho_\nu)\mathbf{e}^{i\theta}) \\ \approx (f + \delta f)(\mathbf{c}_\nu + \rho_\nu\mathbf{e}^{i\theta}) + f'(\mathbf{c}_\nu + \rho_\nu\mathbf{e}^{i\theta})(\delta\mathbf{c}_\nu + \delta\rho_\nu\mathbf{e}^{i\theta}). \end{aligned}$$

- Setting the RHS of these approximations equal gives

$$\begin{aligned} (f + \delta f)(\mathbf{c}_\nu + \rho_\nu\mathbf{e}^{i\theta}) = \gamma_\nu(\mathbf{S}_\nu(\theta)) + \gamma'_\nu(\mathbf{S}_\nu(\theta))U_\nu(\theta) \\ - f'(\mathbf{c}_\nu + \rho_\nu\mathbf{e}^{i\theta})(\delta\mathbf{c}_\nu + \delta\rho_\nu\mathbf{e}^{i\theta}). \end{aligned}$$

# Linearization

More concisely

- For convenience define
  - ▶  $\xi_\nu(\theta) := \gamma_\nu(\mathbf{S}_\nu(\theta))$ ,
  - ▶  $\eta_\nu(\theta) := \gamma'_\nu(\mathbf{S}_\nu(\theta))$ , and
  - ▶  $\zeta_\nu(\theta) := -f'(\mathbf{c}_\nu + \rho_\nu \mathbf{e}^{i\theta})\mathbf{e}^{i\theta} = i\rho_\nu^{-1}\eta_\nu \mathbf{S}'_\nu(\theta)$ .
- The linearization conditions can then be written
  - ▶  $(f + \delta f)(\mathbf{e}^{i\theta}) = \xi_1(\theta) + \eta_1(\theta)U_1(\theta)$
  - ▶  $(f + \delta f)(\mathbf{c}_\nu + \rho_\nu \mathbf{e}^{i\theta}) = \xi_\nu(\theta) + \eta_\nu(\theta)U_\nu(\theta) + \zeta_\nu(\theta)(\delta\rho_\nu + \delta\mathbf{c}_\nu \mathbf{e}^{-i\theta})$

for the updates around  $\mathbf{C}_1$  and around  $\mathbf{C}_\nu$ ,  $2 \leq \nu \leq m$ , respectively.

# Newton Updates

- After the linear system has been solved, the updates are applied at each step ( $n$ ) as follows:

- ▶  $S_\nu^{(n)}(\theta) = S_\nu^{(n-1)}(\theta) + U_\nu^{(n-1)}(\theta)$

for  $1 \leq \nu \leq m$ , and

- ▶  $c_\nu^{(n)} = c_\nu^{(n-1)} + \delta c_\nu^{(n-1)}$

- ▶  $\rho_\nu^{(n)} = \rho_\nu^{(n-1)} + \delta \rho_\nu^{(n-1)}$

for  $2 \leq \nu \leq m$ .

# Discrete analyticity conditions

- $$a_{1,-(k+1)} - \sum_{\nu=2}^m \sum_{j=0}^k \binom{k}{j} \rho_{\nu}^{j+1} c_{\nu}^{k-j} a_{\nu,-(j+1)} = 0,$$

- $$\sum_{j=0}^{M-1} B_{k+1,j} \rho_{\ell}^k c_{\ell}^j a_{1,k+j} - a_{\ell,k}$$

- $$- \sum_{\substack{\nu=2 \\ \nu \neq \ell}}^m \sum_{j=0}^{M-1} \frac{\rho_{\ell}^k}{(c_{\nu} - c_{\ell})^{k+1}} B_{k+1,j} \frac{\rho_{\nu}^{j+1}}{(c_{\ell} - c_{\nu})^j} a_{\nu,-(j+1)} = 0,$$

- $$\sum_{j=0}^{M-1} a_{1,j} z_0^j + \sum_{\nu=2}^m \sum_{j=1}^M a_{\nu,-j} \left( \frac{\rho_{\nu}}{z_0 - c_{\nu}} \right)^j = w_0.$$

# Matrix Form

## of the Analyticity and Normalization Conditions

- The discrete system of equations can be written

$$P\underline{a} = P_1\underline{a}_1 + \cdots + P_m\underline{a}_m = [P_1 \quad \cdots \quad P_m] \begin{bmatrix} \underline{a}_1 \\ \vdots \\ \underline{a}_m \end{bmatrix} = \begin{bmatrix} 0 \\ \vdots \\ 0 \\ w_0 \end{bmatrix} := \underline{r}.$$

# Discrete Linearization Conditions

- We need to define the vectors and vector functions
  - ▶  $\underline{\theta} := \frac{2\pi}{N}(0, 1, \dots, N-1)^T$ ,
  - ▶  $\underline{\xi}_\nu := \xi_\nu(\underline{\theta})$ ,
  - ▶ and similarly for  $\underline{\eta}_\nu$ ,  $\underline{\zeta}_\nu$ , and  $\underline{U}_\nu$ .
- If  $F$  is the discrete Fourier transform matrix,  $E_\nu := \text{diag}(\underline{\eta}_\nu)$ ,  $\underline{q} := e^{-i\underline{\theta}}$ , and  $*$  is the Hadamard product, then the linearization conditions become
  - ▶  $N\underline{a}_1 = F\underline{\xi}_1 + FE_1\underline{U}_1$  and
  - ▶  $N\underline{a}_\nu = F\underline{\xi}_\nu + FE_\nu\underline{U}_\nu + \delta\rho_\nu F\underline{\zeta}_\nu + \delta c_\nu F(\underline{q} * \underline{\zeta}_\nu)$ .



# New Linear System

- For ease of exposition, assume  $m = 3$  for the rest of this section.
- Combining the discrete system of equations for the analyticity and normalization conditions with the discretized linear conditions gives

$$\begin{aligned}
 & P_1 F E_1 \underline{U}_1 \\
 & + P_2 (F E_2 \underline{U}_2 + \delta \rho_2 F \underline{\zeta}_2 + (\operatorname{Re} \delta \mathbf{c}_2 + i \operatorname{Im} \delta \mathbf{c}_2) F(\underline{q} * \underline{\zeta}_2)) \\
 & + P_3 (F E_2 \underline{U}_3 + \delta \rho_3 F \underline{\zeta}_3 + (\operatorname{Re} \delta \mathbf{c}_3 + i \operatorname{Im} \delta \mathbf{c}_3) F(\underline{q} * \underline{\zeta}_3)) \\
 & = \underline{N} \underline{r} - P_1 F \underline{\xi}_1 - P_2 F \underline{\xi}_2 - P_3 F \underline{\xi}_3 := \underline{\tilde{g}}.
 \end{aligned}$$

# More Convenience Notation

- Let  $\underline{w}_\nu := P_\nu F \underline{\zeta}_\nu$ ,
- $\underline{wq}_\nu := P_\nu F(q * \underline{\zeta}_\nu)$ ,
- $W := \begin{bmatrix} \underline{w}_2 & \underline{w}_3 & \underline{wq}_2 & i\underline{wq}_2 & \underline{wq}_3 & i\underline{wq}_3 \end{bmatrix}$ ,
- and of course  $P := [P_1 \quad P_2 \quad P_3]$ .
- Also define the real vector  $\underline{U} :=$

$$\left[ \underline{U}_1^T \quad \underline{U}_2^T \quad \underline{U}_3^T \quad \delta\rho_2 \quad \delta\rho_3 \quad \operatorname{Re} \delta c_2 \quad \operatorname{Im} \delta c_2 \quad \operatorname{Re} \delta c_3 \quad \operatorname{Im} \delta c_3 \right]^T.$$

# The Matrix $\tilde{D}$

- Combining all of this we now have

$$\tilde{D}\underline{U} := \begin{bmatrix} P_1 & P_2 & P_3 & W \end{bmatrix} \begin{bmatrix} F & 0 & 0 & 0 \\ 0 & F & 0 & 0 \\ 0 & 0 & F & 0 \\ 0 & 0 & 0 & I \end{bmatrix} \begin{bmatrix} E_1 & 0 & 0 & 0 \\ 0 & E_2 & 0 & 0 \\ 0 & 0 & E_3 & 0 \\ 0 & 0 & 0 & I \end{bmatrix} \underline{U} = \underline{\tilde{g}}.$$

# The Matrix $D$

Through normalization

- We add a row to this system to force  $U_1(0) = 0$  at every iteration.
- This satisfies the normalization condition  $f(1) = \gamma_1(0)$ .
- To do this define the vector  $\underline{v}^T := (1, 0, \dots, 0)$ , and then

$$D := \begin{bmatrix} \tilde{D} \\ \frac{\sqrt{N}}{2} \underline{v}^T \end{bmatrix} \quad \text{and} \quad \underline{g} := \begin{bmatrix} \tilde{g} \\ 0 \end{bmatrix}.$$

# The Matrix $A$

- Taking the “normal equations” and using the fact  $\underline{U}$  is real,

$$\underline{AU} := \frac{2}{N} \operatorname{Re}(D^H D) \underline{U} = \frac{2}{N} \operatorname{Re}(D^H \underline{g}) := \underline{b}.$$

- This system can now be solved efficiently using the conjugate gradient method.

# The Matrix $A$ Decomposed

- Define

- ▶  $A_{kj} := (2/N)\text{Re}(E_k^H F^H P_k^H P_j F E_j)$  and
- ▶  $X_k := (2/N)\text{Re}(E_k^H F^H P_k^H W)$ .

- Then  $A$  can be written

$$A = \frac{2}{N}\text{Re}(D^H D) = \begin{bmatrix} A_{11} & A_{12} & A_{13} & X_1 \\ A_{21} & A_{22} & A_{23} & X_2 \\ A_{31} & A_{32} & A_{33} & X_3 \\ X_1^T & X_2^T & X_3^T & W^H W \end{bmatrix} + \frac{1}{2}vv^T,$$

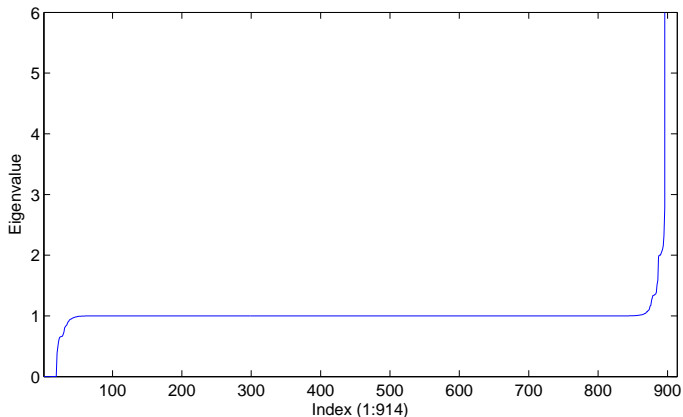
# Eigenvalues of $A$

- To understand the eigenvalues of  $A$  it suffices to examine the submatrix

$$\hat{A} = \begin{bmatrix} A_{11} & A_{12} & A_{13} \\ A_{21} & A_{22} & A_{23} \\ A_{31} & A_{32} & A_{33} \end{bmatrix}.$$

- For the eigenvalues:
  - ▶ The diagonal entries can be shown to be **discretizations of the identity plus a compact operator**, and
  - ▶ the off-diagonal entries can be shown to be **discretizations of a compact operator**.
- In effect  $\hat{A}$  is a **low-rank perturbation of the identity**, and the eigenvalues cluster around 1.
- This is the property which makes the conjugate gradient method an efficient solver to use for this problem.

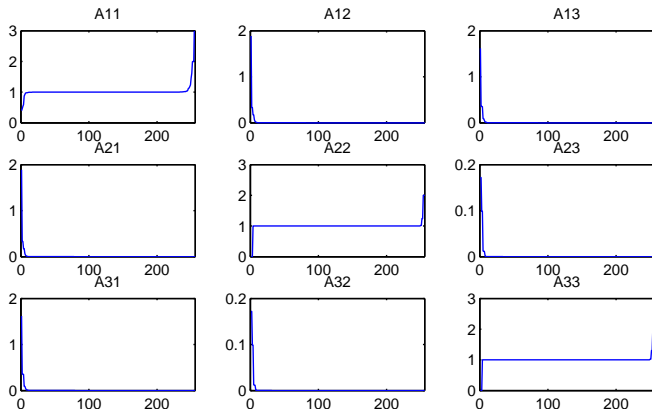
# Eigenvalues of $A$ Cluster Around 1



- This map had  $m = 7$  and  $N = 128$ .



# Eigenvalues of $\hat{A}$



- This map had connectivity  $m = 3$  with  $N = 256$ .

# Remarks and future work

- The extensions of Fornberg's original method are essentially complete.  $I + compact$  inner systems carry over.
- (The ellipse method was not presented here.)
- The MATLAB codes need to be refined and integrated.
- Further comparisons with Wegmann's methods needs to be done