

## ON BIFURCATIONS OF A HOMOCLINIC "FIGURE EIGHT" FOR A SADDLE WITH A NEGATIVE SADDLE VALUE

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Consider a dynamical system  $X_0$  of class  $C^2$  given on a  $C^2$ -smooth  $m$ -dimensional manifold. Suppose that  $X_0$  has an equilibrium state  $O$  of saddle type. Let  $\lambda_i$ ,  $i = 1, \dots, m$ , be the roots of the characteristic equation of the system at  $O$ . We suppose that  $\lambda_m > 0$  and  $\operatorname{Re} \lambda_i < 0$ ,  $i = 1, \dots, m-1$ . In this case the stable manifold  $W^s$  of the saddle is  $(m-1)$ -dimensional and the unstable manifold  $W^u$  is one-dimensional. Suppose that both the orbits  $\Gamma_0^+$  and  $\Gamma_0^-$  leaving the saddle return to the saddle as  $t \rightarrow +\infty$ . Suppose also that the saddle value  $\sigma = \lambda_m + \max_{i=1, \dots, m-1} \operatorname{Re} \lambda_i$  is negative.

**THEOREM 1.** *There is a neighborhood  $V$  of the contour  $\Gamma_0^+ \cup \Gamma_0^- \cup O$  such that for any system  $X$  sufficiently close to  $X_0$  in the  $C^2$ -topology the set of nonwandering orbits of  $X$  in  $V$  consists of the point  $O$  and one of the following:*

- 1) one or two stable limit cycles, or
- 2) one or two homoclinic saddle curves, or
- 3) a stable limit cycle and a homoclinic saddle curve, or
- 4) a quasiminimal set.

*In the last case both the separatrices leaving the saddle will be Poisson  $P^+$ -stable.*

Denote by  $W^s(X)$  and  $W^u(X)$  the stable and unstable manifolds of the saddle point  $O(X)$  for the system  $X$  close to  $X_0$ , and let  $\Gamma^+(X)$  and  $\Gamma^-(X)$  be the orbits leaving the saddle point. We introduce local coordinates  $x_i$ ,  $i = 1, \dots, m$ , in a neighborhood of  $O(X)$  so that the equation of  $W^u(X)$  is  $x_1 = 0, \dots, x_{m-1} = 0$ , and the equation of  $W^s(X)$  is  $x_m = 0$ .

We shall suppose that  $\Gamma^+(X)$  exits into the region  $x_m > 0$ , and  $\Gamma^-(X)$  into the region  $x_m < 0$ . Clearly, for  $r$  and  $d$  sufficiently small the surface  $\pi: x_1^2 + \dots + x_{m-1}^2 = r^2$ ,  $|x_m| \leq d$  will be transverse to the flow. Assume that  $\pi_0 = \{M(x_1, \dots, x_m) \in \pi | x_m = 0\}$  separates  $\pi$  into two components  $\pi_+ = \{M(x_1, \dots, x_m) \in \pi | x_m > 0\}$  and  $\pi_- = \{M(x_1, \dots, x_m) \in \pi | x_m < 0\}$ . According to [1], for  $X$  sufficiently close to  $X_0$  and for  $r^2 + d^2$  sufficiently small it is possible to define maps  $T_+: \pi_+ \rightarrow \pi$  and  $T_-: \pi_- \rightarrow \pi$  such that  $T_+(M) \rightarrow M^+$  as  $x_m \rightarrow^+ 0$  and  $T_-(M) \rightarrow M^-$  as  $x_m \rightarrow^- 0$ . Here  $M^+(a_1^+, \dots, a_m^+)$  and  $M^-(a_1^-, \dots, a_m^-)$  denote the points of first intersection of  $\Gamma^+(X)$  and  $\Gamma^-(X)$  with  $\pi$ . In the case of  $X_0$  the points  $M^+$  and  $M^-$  belong to  $\pi_0$ , and so  $a_m^+ = a_m^- = 0$ .

Consider the sequences of points  $\{M_i^+\}$  and  $\{M_i^-\}$  in which  $\Gamma^+(X)$  and  $\Gamma^-(X)$  intersect  $\pi$ . Define sequences  $S^+ = \{S_i^+\}_{i=0}^{+\infty}$  and  $S^- = \{S_i^-\}_{i=0}^{+\infty}$  of symbols from the alphabet  $\{-1, 0, 1\}$  as follows:  $S_0^+ = 1$ ,  $S_0^- = -1$ , while  $S_i^* = 1$  if  $M_i^* \in \pi_+$ ,  $S_i^* = -1$  if  $M_i^* \in \pi_-$ , and  $S_i^* = 0$  if  $M_j^* \in \pi_0$  for some  $j \leq i$  (where  $*$   $\in \{+, -\}$ ). Clearly if  $\Gamma^*(X)$  returns to the saddle as  $t \rightarrow +\infty$  then there is some  $j$  such that  $S_i^* = 0$  for all  $i \geq j$ . We call such a homoclinic orbit an *orbit of type  $s = \{S_0^* \dots S_{j-1}^*\}$* . A periodic orbit of  $X$  that lies in  $V$  and is homotopic in  $V$  to a homoclinic orbit of type  $s$  is called a *cycle of type  $s$* , with  $s$  being some finite word in the alphabet  $\{-1, 1\}$ .

Next we construct a binary tree as follows: at the first vertex we place the symbol pair  $(1, -1)$ ; from this two arrows go to the vertices  $(1, -1, 1)$  and  $(1, -1, -1)$ , and so

on by the rule that from a vertex  $(p, s)$  there are arrows going to the vertices  $(p, sp)$  and  $(ps, s)$ , where  $p$  and  $s$  denote finite words in the alphabet  $\{-1, 1\}$ . We call a finite word-pair  $(p, s)$  in the alphabet  $\{-1, 1\}$  *admissible* if it is at one of the vertices of the tree so constructed. An infinite word-pair  $(p, s)$  is called *admissible* if there is a sequence of admissible finite pairs  $(p_i, s_i)$  such that each  $p_i$  is a prefix of  $p$ , each  $s_i$  is a prefix of  $s$ , the lengths of  $p_i$  and  $s_i$  approach infinity as  $i \rightarrow \infty$ , and for every  $i$  the pair  $(p_{i+1}, s_{i+1})$  belongs to the subtree with initial vertex  $(p_i, s_i)$ . A word  $s$  is *admissible* if it is an element of an admissible pair.

Let us note some properties of the tree of admissible pairs:

- 1) Each finite admissible pair is encountered in the tree only once.
- 2) If a finite admissible word appears as an element of two admissible pairs, then one of these pairs belongs to the subtree starting at the other pair.
- 3) Each infinite admissible word appears as an element of only one admissible pair.

**THEOREM 2.** *There exists a neighborhood  $V$  of the contour  $\Gamma_0^+ \cup \Gamma_0^- \cup O$  such that for any system  $X$  sufficiently close to  $X_0$  in the  $C^2$ -topology the limit cycles and homoclinic orbits that lie in  $V$  can have only admissible types. In the case of two limit cycles or two homoclinic saddle curves or a pair consisting of a limit cycle and a homoclinic saddle curve the types of these orbits are an admissible pair. If  $\Gamma^+(X)$  and  $\Gamma^-(X)$  are  $P^+$ -stable, then the pair  $(S^+, S^-)$  is admissible.*

In the general case systems with two homoclinic saddle curves constitute sets of codimension two, distinguished by the following conditions: 1')  $\lambda_1$  is complex and  $\operatorname{Re} \lambda_1 = \operatorname{Re} \lambda_2 > \operatorname{Re} \lambda_i$ ,  $i = 3, 4, \dots, m-1$ , or 1'')  $\lambda_1$  is real and  $\lambda_1 > \operatorname{Re} \lambda_i$ ,  $i = 2, 3, \dots, m-1$ ; 2)  $\Gamma_0^+$  and  $\Gamma_0^-$  do not lie in a lower-dimensional submanifold of  $W^s$ ; and 3) the separatrix parameters (the quantity  $\delta$  in the notation of [2] and  $A$  in the notation of [3]) are different from zero. In view of this we shall now consider two-parameter families  $X_\mu$  of  $C^2$ -smooth dynamical systems that contain  $X_0$  and depend smoothly on  $\mu = (\mu_+, \mu_-)$ . The coordinates  $a_m^+$  and  $a_m^-$  of the points  $M^+$  and  $M^-$  will be smooth functions of  $\mu$  with  $a_m^+(0) = a_m^-(0) = 0$ . We shall suppose that  $\mu_+ = a_m^+(\mu)$  and  $\mu_- = a_m^-(\mu)$ .

Let  $C_s$  denote the bifurcation set in the  $(\mu_+, \mu_-)$ -plane that corresponds to the existence of a homoclinic orbit of type  $s$ . This  $C_s$  is a curve, given either by an equation  $\mu_+ = h_s(\mu_-)$  or by  $\mu_- = h_s(\mu_+)$ , where  $h_s$  is a function with Lipschitz constant less than 1, defined on some open subset of  $R^1$ .

In the case when  $\lambda_1$  is complex all possibilities for the family  $X_\mu$  allowed by Theorems 1 and 2 are realized. The bifurcation diagram for this case is shown in Figure 1. The configuration of bifurcation curves along which homoclinic saddle curves exist is as follows:  $\mu_+ = 0$  is the curve  $C_1$ ,  $\mu_- = 0$  is the curve  $C_{-1}$ , while two further curves  $C_{1-1}$  and  $C_{-1-1}$  also leave the point  $(0, 0)$ ; the curves  $C_{1-1}$  and  $C_{-1-1}$  intersect  $C_{-1}$  and  $C_1$  respectively at infinitely many points. Continue according to this rule: let  $(p, s) \neq (1, -1)$  be an admissible pair; then  $C_p$  and  $C_s$  intersect at infinitely many points, and if  $P$  and  $Q$  are neighboring points of intersection of  $C_p$  and  $C_s$  such that  $h_p > h_s$  on the interval between  $P$  and  $Q$ , then  $P$  and  $Q$  are further connected by curves  $C_{ps}$  and  $C_{sp}$ . The region bounded by  $C_{ps}$  and  $C_{sp}$  corresponds to the existence of a cycle of type  $ps$ ; if  $h_p < h_s$  on the interval between  $P$  and  $Q$  then the region bounded by the segments of the curves  $C_p$  and  $C_s$  from  $P$  to  $Q$  corresponds to the existence of a pair of cycles of types  $p$  and  $s$ . To the points of the set  $F = \operatorname{cl}(\bigcup_s C_s) \setminus \bigcup_s C_s$  (the union taken over all finite admissible words  $s$ ) correspond quasiminimal sets.

In the case of real  $\lambda_1$  the bifurcation diagram depends on the separatrix parameters  $A_+$  and  $A_-$  and on the relative position of the orbits  $\Gamma_0^+$  and  $\Gamma_0^-$ .

Below we consider the case where  $\Gamma_0^+$  and  $\Gamma_0^-$  arrive at the saddle tangent to each other. Note that this case was considered in [4], where sufficient conditions were given for the existence of cycles of types  $\{1\}$ ,  $\{-1\}$ , and  $\{1-1\}$ .

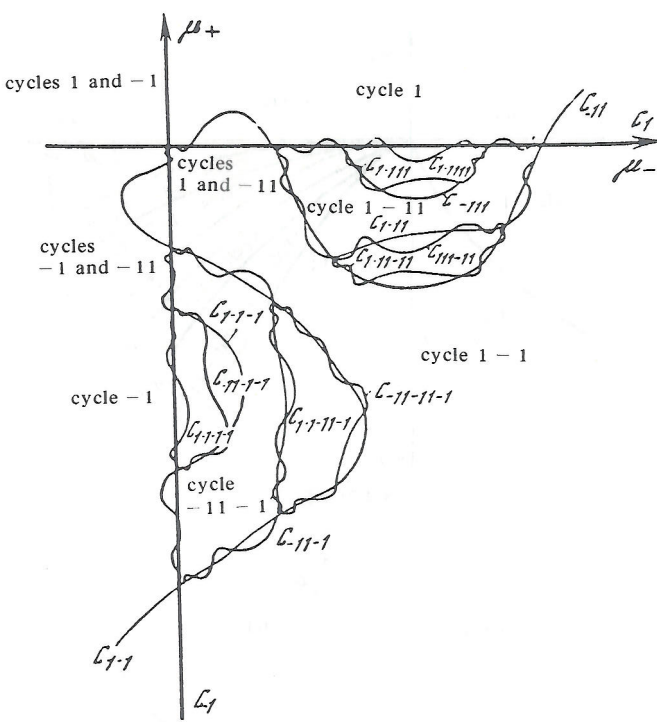


FIGURE 1

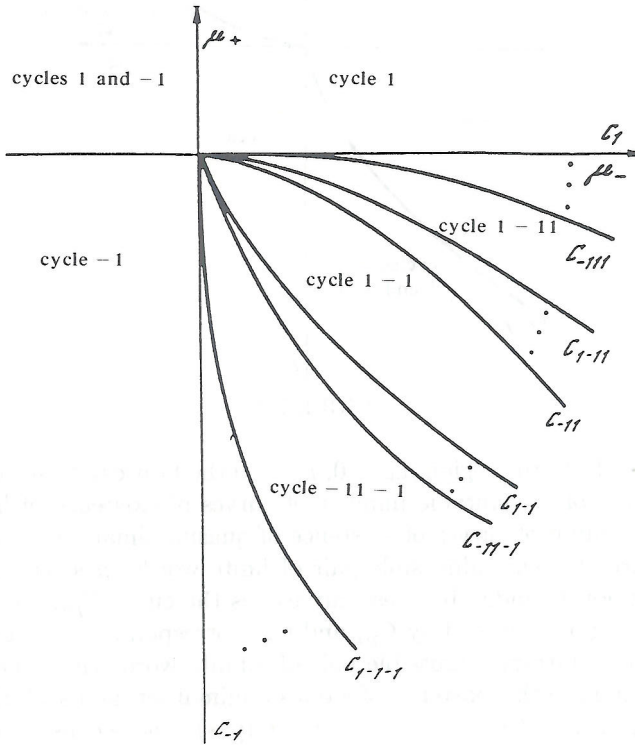


FIGURE 2

In the case  $A_+ > 0$ ,  $A_- > 0$  (see Figure 2) the region  $\mu_+ > 0$ ,  $\mu_- < 0$  corresponds to the existence of a pair of cycles of types  $\{1\}$  and  $\{-1\}$ , the region  $\mu_+ > 0$ ,  $\mu_- > 0$  to the existence of a unique cycle of type  $\{1\}$ , and the region  $\mu_+ < 0$ ,  $\mu_- < 0$  to the existence of

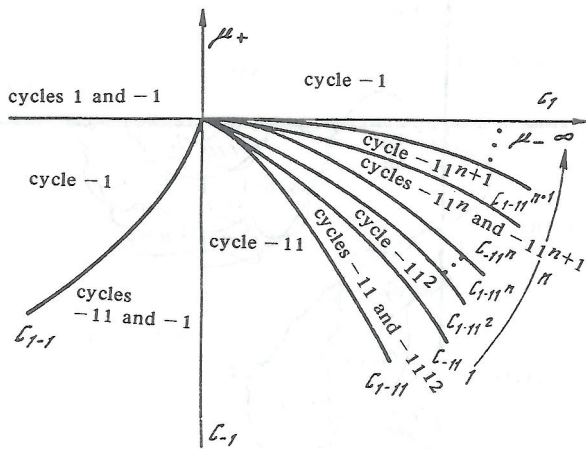


FIGURE 3

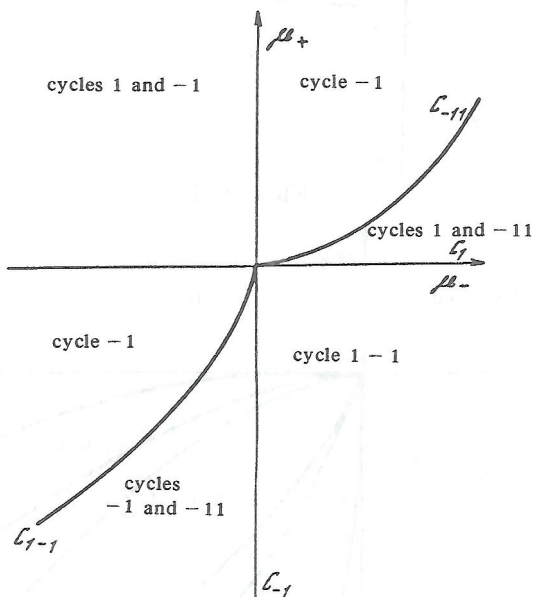


FIGURE 4

a cycle of type  $\{-1\}$ . In the region  $\mu_+ < 0, \mu_- > 0$  the bifurcation set is a Cantor pencil of curves consisting of a countable number of curves of existence of homoclinic saddle curves and a continuum of curves of existence of quasiminimal sets. The region has the following structure: for any admissible pair of finite words  $(p, s)$  there exist curves  $C_p$  and  $C_s$ ; in the region bounded by these curves lies the curve  $C_{ps}$ , and between  $C_p$  and  $C_{ps}$  lies  $C_{sp}$ ; the region bounded by  $C_{ps}$  and  $C_{sp}$  corresponds to the existence of cycles of type  $ps$ . For an arbitrary admissible pair of infinite words  $(p, s)$  there exists a curve  $C(p, s)$  corresponding to the existence of a quasiminimal set, and such that if  $\mu \in C(p, s)$  then  $S^+(X_\mu) = p$  and  $S^-(X_\mu) = s$ . The curve  $C(p, s)$  can be constructed as

$$\lim_{i \rightarrow \infty} C_{s_i} = \lim_{i \rightarrow \infty} C_{p_i},$$

where  $(p_i, s_i)$  is a sequence of admissible pairs approximating  $(p, s)$ .

In the case  $A_+ > 0, A_- < 0$  (see Figure 3) there exist cycles only of types  $\{1\}$ ,  $\{-1\}$ , and  $\{-1 1^n\}$ ,  $n = 1, 2, \dots$  (here  $1^n$  means the word consisting of  $n$  ones), and

the parameter plane is partitioned into a countable number of regions by the curves  $C_1$ ,  $C_{-1}$ ,  $C_{1-1}$ ,  $C_{-1-1}$ , and  $C_{1-1-1}$ ,  $n = 1, \dots, \infty$ .

In the case  $A_+ < 0$ ,  $A_- < 0$  (see Figure 4) there exist cycles only of types  $\{1\}$ ,  $\{-1\}$ , and  $\{1-1\}$ ; the parameter plane here is partitioned into 6 regions.

The case when  $\Gamma_0^+$  and  $\Gamma_0^-$  arrive at the saddle from opposite directions has been studied in [5]. In this case the system  $X_\mu$  has no Poisson stable nonclosed orbits, and the cycles are only of types  $\{1\}$ ,  $\{-1\}$ ,  $\{1-1\}$ ,  $\{1(-1)^n\}$ , and  $\{-1(1-1)^n\}$ ,  $n = 1, \dots, \infty$ . In the cases  $A_+ > 0$ ,  $A_- > 0$  and  $A_+ < 0$ ,  $A_- > 0$  the bifurcation set consists of a finite number of curves, and in the case  $A_+ < 0$ ,  $A_- < 0$  it consists of countably many curves.

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